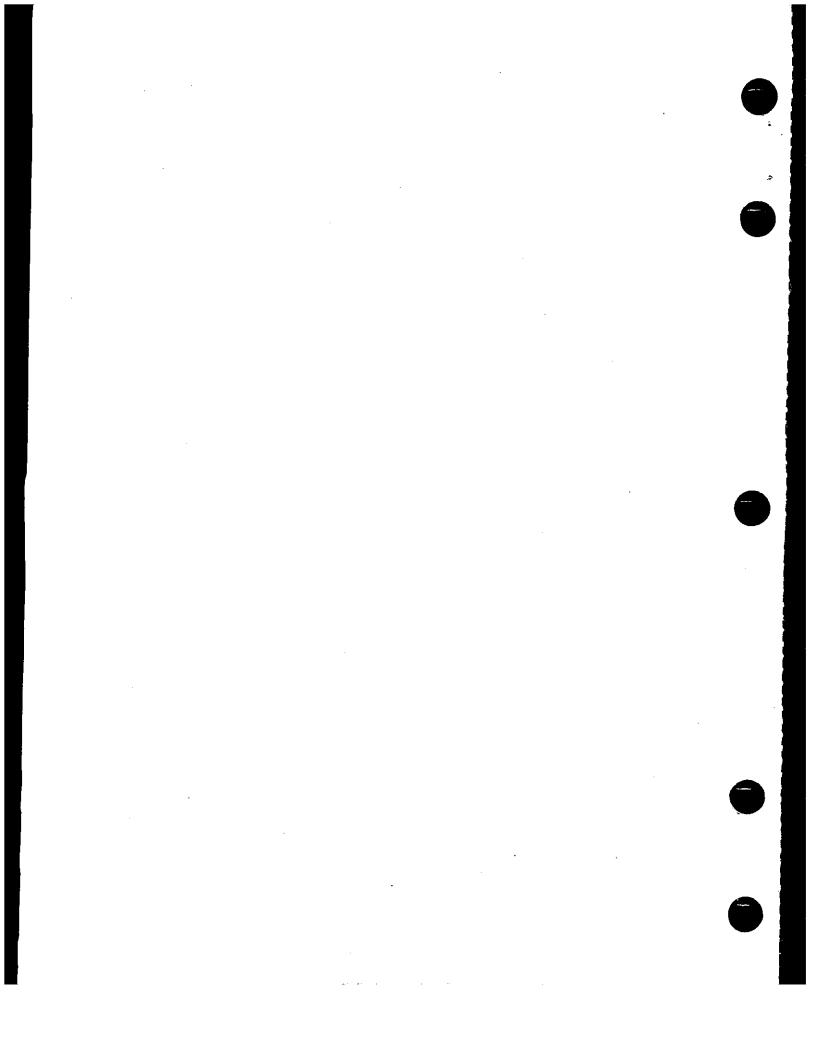
SECTION III - CONSUMABLES ANALYSIS



## NOTE

Acknowledgement is made to the Consumables Analysis Section (CAS) of the Mission Planning and Analysis Division (MPAD) for their work in the preparation of the RCS and cryogenics consumable analysis presented herein.

## AS503/103 PROPELLANT BUDGET

The results of the SM, CM, and SPS propellant budget analysis are sumarized in the following tables and figures:

| TABLE 3-I      | SM-RCS PROPELLANT LOADING          | 3-3  |  |
|----------------|------------------------------------|------|--|
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| Ground Rules . | and Assumption                     |      |  |

## Ground Rules and Assumption

The ground rules and assumptions listed below were used in the construction of the SM-RCS budget.

- 1. <u>Data Source</u>: Data for SM-RCS engine performance and propellant requirements were obtained from Part 4, Volume I of the CSM/LM Spacecraft Operational Data Book, May 1968.
- 2. Maneuvers: Since it is impossible to predict in all cases what maneuvers rates or angles will be required, it was assumed that all maneuvers were 3 axis at rates from 0.2 deg/sec to 0.5 deg/sec (unless otherwise noted). Angles were varied as a function of the maneuver requirements. It was also assumed that all IMU alignments

required 3 axis orientations with allowances for minimum impulse control, which may seem conservative, but would allow for unscheduled attitude maneuvers. An increase in passive thermal control (PTC) requirements was made to allow for active control of the non spin axis. Predicted costs are 1.3 lbs/hr translunar and 1.4 lbs/hrs transearth with a total increase of 100 lbs to the budget. Navigation sightings, like the IMU alignments, were predicted at the same cost for all cases. Realizing that some navigation sightings will be easier to accomplish than others, a nominal cost of approximately 1.2 lbs to 1.4 lbs per set was predicted. Lunar orbit maneuvers were budgeted to the lunar orbit attitude timeline. Midcourse translations were budgeted as SM-RCS corrections of 3 fps and 7 fps translunar and 10 fps, 5 fps, and 2 fps transearth. The 7 fps correction could possibly be replaced by a SPS burn since it is 2 fps above the minimum SPS burn time for translumar corrections.

3. Flow Rates: A propellant flow rate of 0.361 lbs/sec/engine was assumed for steady state operation. A minimum impulse burn has been predicted at a maximum 0.005 lbs per pulse.

TABLE 3-I

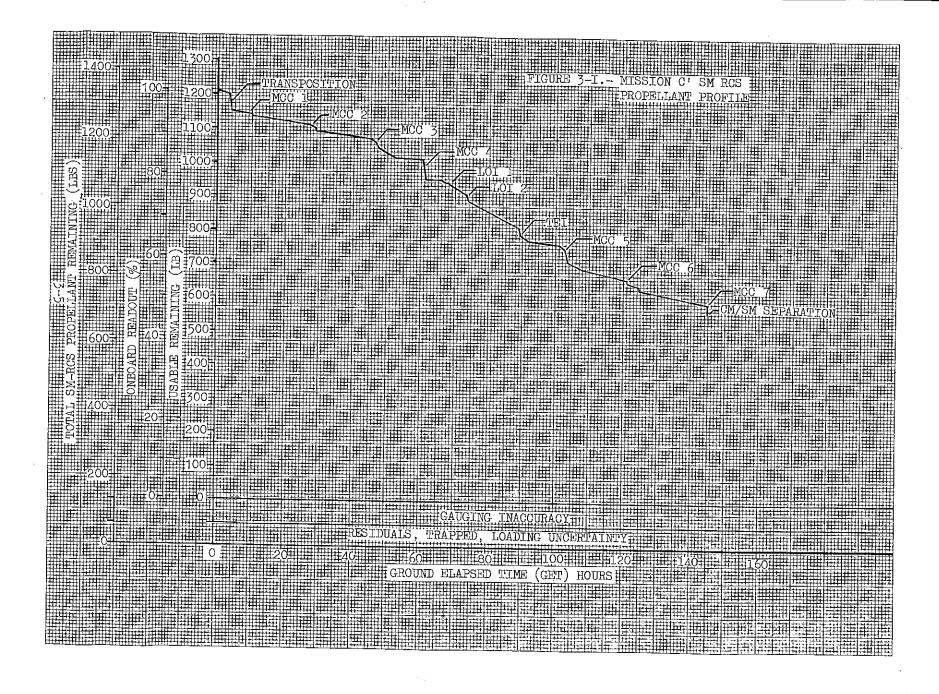
## SM-RCS PROPELLANT LOADING

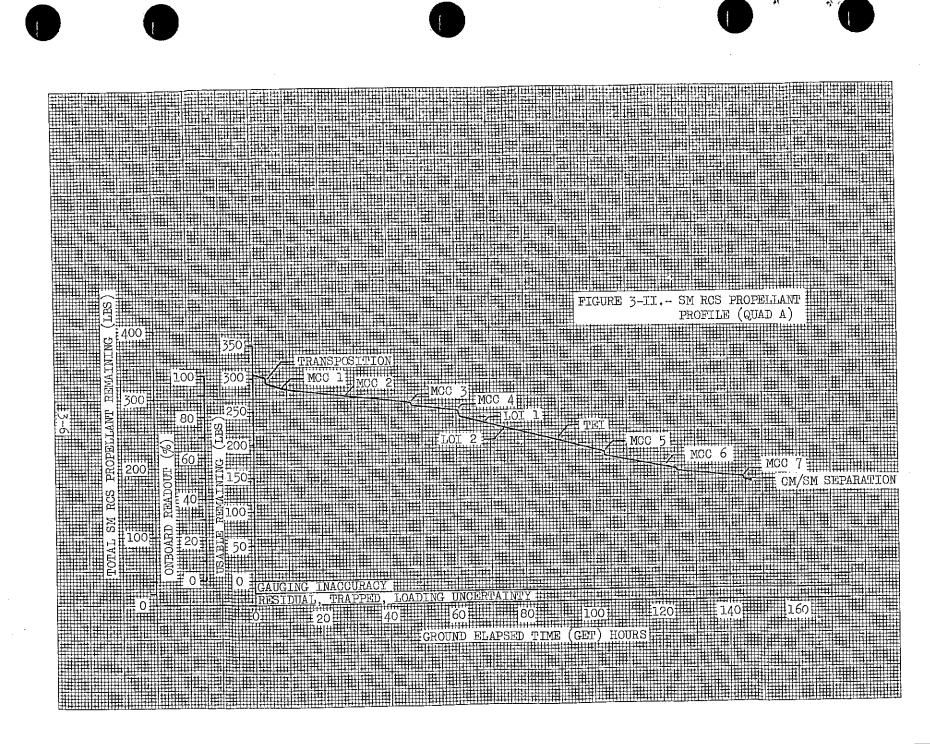
|                                   | SM-RCS-LBS   |
|-----------------------------------|--------------|
| Nominal Loaded                    | 1347.6       |
| Unusable (trapped)                | 26.8         |
| Total Deliverable                 | 1320.8       |
| Loading Uncertainty (temperature) | <u> 36.8</u> |
|                                   | 1284.0       |
| Gauging Inaccuracy                | 72.0         |
|                                   | 1212.0       |
| *Mixture Ratio Uncertainty        | 82.0         |
|                                   | 1130.0       |
| Total Used                        | 655.8        |
| Operational Margin                | 474.2        |

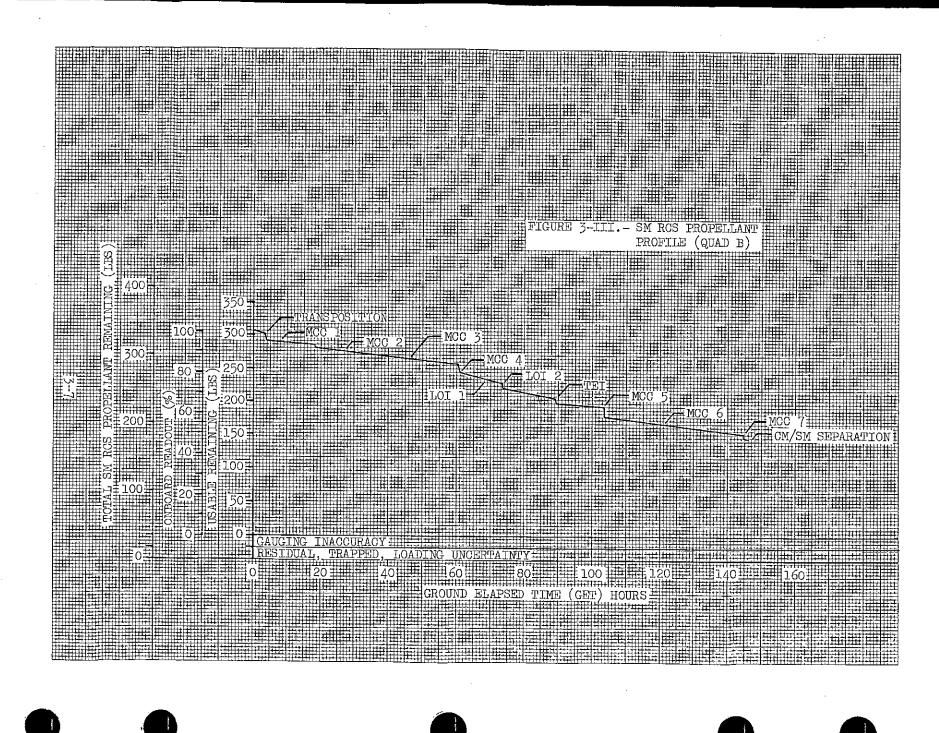
\*This quantity is based on the flight plan and results from the use of approximately 460 lbs of RCS for attitude orientation and control. This is considered unusable for mission planning and represents a dispersion to the nominal profile.

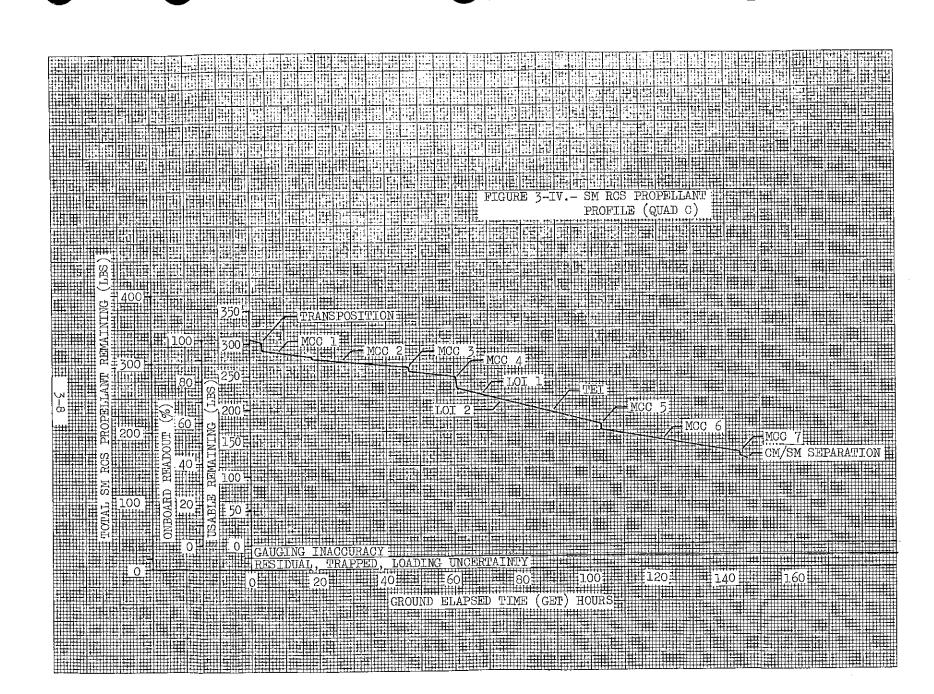
TABLE 3-II
SM RCS USAGE SUMMARY

|   |                     | PROPELLA | ANT USED, LBS | PROPELLANT | REMAINING, LBS |
|---|---------------------|----------|---------------|------------|----------------|
|   | Day (GET, HRS)      | PER DAY  | ACCUMULATIVE  | TOTAL      | USABLE         |
| ) |                     |          | •             | 1347.6     | 1130.0         |
| , | PRELAUNCH           | 5.8      | 5.8           | 1341.8     | 1124.2         |
|   | 1 (00:00 - 24:00)   | 99.6     | 105.4         | 1242.2     | 1024.6         |
|   | 2 (24:00 - 48:00)   | 79.9     | 185.3         | 1162.3     | 944.7          |
|   | 3 (48:00 - 72:00)   | 110.3    | 295.6         | 1052.0     | 834.4          |
|   | 4 (72:00 - 96:00)   | 147.0    | 442.6         | 905.0      | 687.4          |
|   | 5 (96:00 - 120:00)  | 109.1    | 551.7         | 795.9      | 578.3          |
|   | 6 (120:00 - 144:00) | 89.3     | 641.0         | 706.6      | 489.0          |
|   | 7 (144:00 - 147:00) | 14.8     | 655.8         | 691.8      | 474.2          |
|   |                     |          |               |            |                |









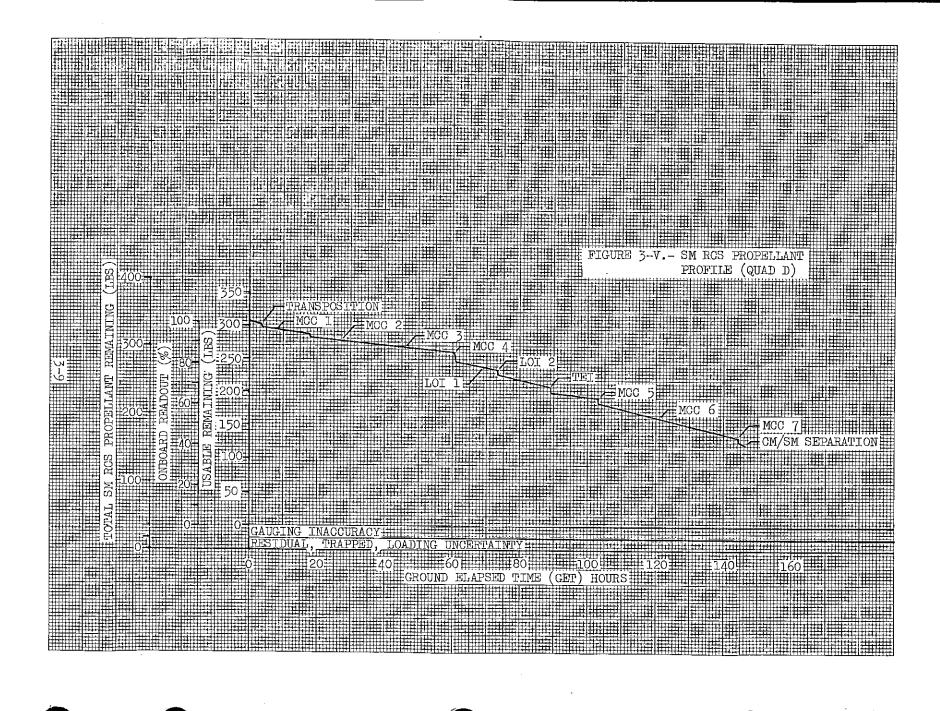


TABLE 3-III

|           | SM-RCS PROPELLANT BU                             | GET    | ·                       |                         |                           |
|-----------|--|--------|-------------------------|-------------------------|---------------------------|
| TIME (HR) | EVENT  | S/C WT | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| • 0       | APOLLO 8 C5M 103                                 | 63878. | • 0                     | 1347.6                  | 100.                      |
| • 0       | SM-RCS CHECKOUT<br>FIRE EACH JET ONE SEC.        | 63872. | 5.8                     | 1341*¤                  | 100+                      |
| 3 • 5     | TRANSPOSITION<br>+X TRANS 1 FPS PGNCS            | 63865. | 7.5                     | 1334.3                  | 99.                       |
| 3 • 5     | -X 0.5 FPS                                       | 63880. | 4.8                     | 1329.5                  | 94.                       |
| 3 • 5     | PITCH 4 DEG/SEC                                  | 63853. | 6.9                     | 1322+7                  | 98.                       |
| 3 • 5     | FORMATION FLYING                                 | 63833. | 20.0                    | 1302+7                  | 97.                       |
| 3 • 8     | MANEUVER TO LOCAL VERTICAL                       | 63830. | 3.2                     | 1299+5                  | 96+                       |
| 3 • 8     | ATTITUDE HOLD .5 DEG OB                          | 63830. | * 3                     | 1299 • 2                | 96.                       |
| 3.9       | SEPARATE FROM S-IVB -X 1.5FPS                    | 63816. | 13.7                    | 1285 • 4                | 95.                       |
| 4 • U     | P52 IMU ALIGN                                    | 63815. | 1.1                     | 1284 • 4                | 95.                       |
| 4.3       | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 63814. | . 8                     | 1283 • 5                | 95•                       |
| 4+3       | MIN. IMPULSE MARKING                             | 63814. | . 4                     | 1283+1                  | 95•                       |
| 4 • 3     | NAV SIGHTING SET 2                               | 63813. | . 8                     | 1282+3                  | 95.                       |
| 4 • 3     | MINIMUM IMPULSE MARKING                          | 63812. | . 4                     | 1281+A                  | 95•                       |
| 4 • 3     | NAV SIGHTING SET 3                               | .63812 | .   8                   | 1281 • 1                | 95.                       |

|              | SM-RCS PROPELLANT BUT                            | GET     | ************************************** |                         |                           |
|--------------|--|---------|--|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  | S/C WT  | SM#RCS<br>USEO<br>(LBS)                | SM_RCS<br>LEFT<br>(LBS) | SM.<br>RCS<br>LEFT<br>(%) |
| 4 • 3        | MINIMUM IMPULSE MARKING                          | .63811. | . 4                                    | 1280.4                  | 95.                       |
| 4 • 3        | NAV SIGHTING SET 4                               | 63810.  | • 9                                    | 1279.7                  | 95.                       |
| 4 • 3        | MINIMUM IMPULSE MARKING                          | 63810.  | . 4                                    | 1279+3                  | 95+                       |
| 8 • 0        | PS2 IMU ALIGN                                    | 63809.  | 1.1                                    | 1278 - 2                | 95.                       |
| 8 • 5        | MIDCOURSE CORRECTION 3 AXIS ORIENT PCNCS         | 63808.  | 1 • 1                                  | 1277+;                  | 95.                       |
| 8 + 5        | ATT HOLD D.5 DEG DB                              | 63807.  | ٠٥                                     | 1276+5                  | 95.                       |
| 9•0          | DELTA VEL = NOMINALLY ZERO                       | 63807.  | •0                                     | 1276.5                  | 95.                       |
| 9+1          | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 63806.  | . 6                                    | 1275.7                  | 95.                       |
| 9+1          | MIN. IMPULSE MARKING                             | 63806.  | • 4                                    | 1275 • 3                | 95•                       |
| 9•1          | NAV SIGHTING SET 2                               | 63805.  | . 8                                    | 1274.5                  | 95.                       |
| 9•1          | MINIMUM IMPULSE MARKING                          | 63805.  | . 4                                    | 1274 * n                | 95•                       |
| 9+1          | NAV SIGHTING SET 3                               | 63804.  | . 8                                    | 1273.9                  | 94.                       |
| 9•1          | MINIMUM IMPULSE MARKING                          | 63803.  | . 4                                    | 1272 · A                | 94.                       |
| 9+8          | ORIENT FOR PTC<br>BAXIS 0.2 DEG/SEC              | 63803.  | <b>.</b> 8                             | 1272+0                  | 94.                       |
| 9.8          | ATTITUDE HOLD D.5 DEG DB PGNCS                   | 63802.  | .8                                     | 1271+2                  | 94.                       |

| ·            | SM-RCS PROPELLANT BL                             | DOGET  |                         | 1                       | <u> </u>                  |
|--------------|--|--------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  | S/C WT | SH-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(8) |
| 9•8          | EST. 0.3 DEG/SEC ROLL                            | 63802. | , 3                     | 1270+9                  | 94.                       |
| 9 • 8        | PITCH AND YAW CONTROL                            | 63792. | 9.1                     | 1261 * 8                | 94.                       |
| 16•6.F       | °52 IMU ALIGN                                    | 63791. | 1.1                     | 1260 · g                | 94.                       |
| 17+0         | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 63791. | .8                      | 1259.9                  | 93*                       |
| 17.0         | MIN. IMPULSE MARKING                             | 63790. | • 4                     | 1259.5                  | 93.                       |
| 1.7 • 0      | NAV SIGHTING SET 2                               | 63789. | . 8                     | 1258+4                  | 93.                       |
| 17•0         | MINIMUM IMPULSE MARKING                          | .3789  | -4                      | 1258 + 2                | 93.                       |
| 17.00        | NAV SIGHTING SET 3                               | 63788. | . 8                     | 1257 • 4                | 93                        |
| 17•0         | MINIMUM IMPULSE MARKING                          | 63788. | .4                      | 1257•n                  | 93                        |
| 17.0         | NAV SIGHTING SET 4                               | 63787. | .8                      | 1256+1                  | 93                        |
| 17+0         | MINIMUM IMPULSE MARKING                          | 63786. | . 4                     | 1255•7                  | 93                        |
| 17 • 0       | NAV SIGHTING SET 5                               | 63785. | .8                      | 1254•9                  | 93                        |
| 17.0         | MINIMUM IMPULSE MARKING                          | 63785. | • 4                     | 1254.5                  | 93                        |
| 18•0         | ORIENT FOR PTC<br>3AXIS 0.2 DEG/SEC              | 63784. | . 8                     | 1253•7                  | 93                        |
| 18.0         | ATT HOLD .5 DEG DB PGNCS                         | 63783. | .8                      | 1252.9                  | 93                        |

| -            | SM-RCS PROPELLANT                                | BUDGET          | <del></del>             | ,<br><del></del> .      | <del>, -</del>            |
|--------------|--|-----------------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  | S/C WT<br>(LBS) | SM.RCS<br>USED<br>(LBS) | SM_RCS<br>LEFT<br>(L8S) | SM_<br>RCS<br>LEFT<br>(%) |
| 18•0         | EST. 0.3 DEG/SEC ROLL                            | 63783.          | • 2                     | 1252•4                  | 93.                       |
| 18.0         | PITCH AND YAW CONTROL                            | 63773.          | 10.4                    | 1242.2                  | 92+                       |
| 26•0         | P52 IMU ALIGN                                    | 63772.          | 1.0                     | 1241.2                  | 72.                       |
| 26 • 5       | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 63771.          | .8                      | 1240.4                  | 92,                       |
| 26+5         | MIN IMPULSE MARKING                              | 63771.          | . 4                     | 1240+0                  | 92.                       |
| 26 • 5       | NAV SIGHTING SET 2                               | 63770.          | . 9                     | 1239+1                  | 92.                       |
| 26•5         | MINIMUM IMPULSE MARKING                          | 63769.          | . 4                     | 1238+7                  | 92.                       |
| 26.5         | NAV SIGHTING SET 3                               | 63768.          | . 8                     | 1237 - я                | 92.                       |
| 26+5         | MINIMUM IMPULSE MARKING                          | 63768.          | . 4                     | 1237.4                  | 92.                       |
| 27.5         | MIDCOURSE CORRECTION THANEUVER TO BURN ATT       | 63767.          | 1 . 1                   | 1236.3                  | 92•                       |
| 27 • 5       | ATT HOLD .5 DEG DB PGNCS                         | 63767,          | . 3                     | 1236•;                  | 92.                       |
| 28•0         | DELTA VEL = NOMINALLY ZERO                       | 63767.          | • U                     | 1.36.1                  | 92•                       |
| 28 • 1       | CISLUNAR NAVIGATION STARZEARTH HORIZON ORIENT    | 63766.          | . 8                     | 1235.3                  | 92.                       |
| 28 • 1       | MIN. IMPULSE MARKING                             | 63765.          | • 4                     | 1234 • g                | 92.                       |
| 28 • 1       | NAV SIGHTING SET 2                               | 63765.          | . 8                     | 1234+n                  | 92.                       |

| (HR)  28.1 MINIMUM IMPULSE MARKING  28.1 NAV SIGHTING SET 3  28.1 MINIMUM IMPULSE MARKING  28.1 NAV SIGHTING SET 4  28.1 MINIMUM IMPULSE MARKING  6.2  28.1 MINIMUM IMPULSE MARKING  6.2  28.9 ORIENT FOR PTC 3AXIS 0.2 DEG/SEC  28.9 ATTITUDE HOLD 0.5 DEG DB PGNCS  6.2  28.9 EST. 0.3 DEG/SEC ROLL  6.3 | LBS)                             | USED (LBS) | LEFT                                 | 91.<br>91.<br>91. |
|--|----------------------------------|------------|--------------------------------------|-------------------|
| 28.1 MINIMUM IMPULSE MARKING  28.1 NAV SIGHTING SET 3  28.1 MINIMUM IMPULSE MARKING  28.1 NAV SIGHTING SET 4  28.1 MINIMUM IMPULSE MARKING  6.1  28.1 MINIMUM IMPULSE MARKING  6.2  28.9 ORIENT FOR PTC 3AXIS 0.2 DEG/SEC  28.9 ATTITUDE HOLD 0.5 DEG DB PGNCS  6.2  28.9 EST. 0.3 DEG/SEC ROLL  6.3       | 3763.<br>3763.<br>3762.<br>3762. | . 4        | 1232.7<br>1232.3<br>1231.5<br>1231.0 | 91.<br>91.<br>91. |
| 28.1 MINIMUM IMPULSE MARKING  28.1 NAV SIGHTING SET 4  6  28.1 MINIMUM IMPULSE MARKING  6  28.9 ORIENT FOR PTC 3AXIS 0.2 DEG/SEC  28.9 ATTITUDE HOLD 0.5 DEG DB PGNCS 6  28.9 EST. 0.3 DEG/SEC ROLL  6   | 3762.                            | . 8        | 1232•3<br>1231•5<br>1231•0           | 91.               |
| 28.1 NAV SIGHTING SET 4  28.1 MINIMUM IMPULSE MARKING  6  28.9 ORIENT FOR PTC 3AXIS 0.2 DEG/SEC  28.9 ATTITUDE HOLD 0.5 DEG DB PGNCS 6  28.9 EST. 0.3 DEG/SEC ROLL  6  | 3762.                            | . 8        | 1231.5                               | 91.<br>91.        |
| 28.1 MINIMUM IMPULSE MARKING  28.9 ORIENT FOR PTC 3AXIS 0.2 DEG/SEC  28.9 ATTITUDE HOLD 0.5 DEG DB PGNCS 6  28.9 EST. 0.3 DEG/SEC ROLL  6  | 3762.                            | . 4        | 1231•0                               | 91.               |
| 28.9 ORIENT FOR PTC 3AXIS 0.2 DEG/SEC  28.9 ATTITUDE HOLD 0.5 DEG DB PGNCS 6  28.9 EST. 0.3 DEG/SEC ROLL 6   | 3761.                            | . 8        | 1230.3                               | 91.               |
| 28.9 ATTITUDE HOLD D.5 DEG DB PGNCS 6  28.9 EST. D.3 DEG/SEC ROLL 6  |                                  |            |                                      |                   |
| 28.9 EST. D.3 DEG/SEC ROLL 6   | * 60 / 51                        |            | 1.2.7.13                             | ' ' '             |
| 2007   | 63760.                           | .3         | 1229.9                               | 91                |
| 2007   | 63753.                           | 6.5        | 1222.7                               | 91                |
| 33.8 P52 1MU ALIGN 6   | 63752.                           | 1.1        | 1221.7                               | 91                |
| 34.3 CISLUNAR NAVIGATION STAR/EARTH HORIZON ORIENT   | 63751.                           | .8         | 1220•8                               | 91                |
| 34.3 MIN. IMPULSE MARKING  | 63751.                           | .4         | 1220 • 4                             | 91                |
|  | 63750.                           |            |                                      | 91                |
| 34.3 MINIMUM IMPULSE MARKING 6   | 63750.                           | • 4        | 1219 • 2                             | 9 n<br>9 n        |

|              | SM-RCS PROPELLANT BU                          | nGET            |                         |                         |                           |
|--------------|---|-----------------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EAEML   | S/C WT<br>(LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 34•3         | MINIMUM IMPULSE MARKING                       | 63749.          | • 4                     | 1217.9                  | 90•                       |
| 34•9         | ORIENT FOR PTC<br>3AXIS_D.2 DEG/SEC           | 63748.          | . 8                     | 1217.1                  | 90•                       |
| 34•9         | ATTITUDE HOLD D.5 DEG DB BGNCS                | 63747,          | . 8                     | 1216.4                  | 90•                       |
| 34•9         | ESI. 0.3 DEG/SEC ROLL                         | 63747.          | . 2                     | 1216.1                  | 90•                       |
| 34+9         | PITCH AND YAW CONTROL                         | 63736.          | 11.0                    | 1205.                   | 89.                       |
| 44+5         | P52 IMU ALIGN                                 | 63735.          | 1.1                     | 1204+0                  | 89.                       |
| 45 • 1       | CISLUNAR NAVIGATION STAR/LUNAR HORIZON ORIENT | 63734.          | . 9                     | 1203+1                  | 89.                       |
| 45•1         | MIN. IMPULSE MARKING                          | 63733.          | • 4                     | 1202.7                  | 89.                       |
| 45 • [       | NAV SIGHTING SET 2                            | 63732.          | . 8                     | 1201-8                  | 89.                       |
| 45 • 1       | MINIMUM IMPULSE MARKING                       | 63732.          | .4                      | 1201.4                  | 89.                       |
| 45 • 1       | NAV SIGHTING SET 3                            | 63731.          | • 9                     | 1200.4                  | 89.                       |
| 45 • 1       | MINIMUM IMPULSE MARKING                       | 63731.          | • 4                     | 1200 • 1                | 89.                       |
| 45 • 1       | NAV SIGHTING SET 4                            | 63730.          | . 8                     | 1199.3                  | 89.                       |
| 45 • 1       | MINIMUM IMPULSE MARKING                       | 63730.          | . 4                     | 1198•9                  | 89.                       |
| 45 • 1       | NAV SIGHTING SET 5                            | 63729.          | . 8                     | 1198-1                  | 89.                       |

| *            |  |       |                 |                         |                         |                           |
|--------------|--|-------|-----------------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  |       | S/C WT<br>(LBS) | SM#RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SH-<br>RCS<br>LEFT<br>(%) |
| 45 • 1       | MINIMUM IMPULSE MARKING                          |       | 63728.          | .4                      | 1197•7                  | 89.                       |
| 46 • 4       | PS2 IMU ALIGN                                    |       | 63727.          | . 1+1                   | 1196+6                  | 89                        |
| 46•6         | MIDCOURSE CORRECTION 3 AXIS ORIENT PGNCS         |       | 63726.          | 1.1                     | 1195.5                  | 89                        |
| 46•6         | ATT HOLD 0.5 DEG DB 60                           | รักธร | 63726.          | . 4                     | 1195+1                  | ВЭ                        |
| 47 • 0       | RCS +X TRANS PGNCS 3 FPS                         |       | 63704.          | 22.1                    | 1173 + n                | 87                        |
| 47•2         | CISLUNAR NAVIGATION<br>STAR EARTH HORIZON ORIENT |       | 63703.          | .8                      | 1172.2                  | 87                        |
| 47•2         | MINIMUM IMPULSE MARKING                          |       | 63702.          | . 4                     | 1171.8                  | 87                        |
| 47 + 2       | NAV SIGHTING SET 2                               |       | 63702.          | . 8                     | 1171+0                  | 87                        |
| 47 • 2       | MININUM IMPULSE MARKING                          |       | 63701.          | . 4                     | 1170+4                  | 87                        |
| 47 * 2       | NAV SIGHTING SET 3                               |       | 63700.          | 8.4                     | 1169.я                  | 87                        |
| 47 • 2       | MINIMUM IMPULSE MARKING                          |       | 63700+          | .4                      | 1169.3                  | 87                        |
| 47 • 8       | ORIENT FOR PTC<br>3AXIS 0.2 DEG/SEC              |       | 63699.          | .8                      | 1168.5                  | 87                        |
| 47•8         | ATTITUDE HOLD 0.5 DEG DB PO                      | SNC5  | 63698.          | 8.                      | 1167.8                  | 87                        |
| 47•8         | EST. 0.3 DEG/SEC ROLL                            |       | 63698.          | . 3                     | 1167.5                  | 87                        |
| 47 • 8       | PITCH AND YAW CONTROL                            |       | 63693.          |                         | 1162.3                  | 86.                       |

|                       | SM-RCS PROPELLANT BU                          | nger         | 4                       | <del></del>             |                           |
|-----------------------|---|--------------|-------------------------|-------------------------|---------------------------|
| T <sub>IME</sub> (HR) | EVENT   | S/C WT (LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 51.5                  | P52 IMU ALIGN                                 | 63692.       | . 9                     | 1161•4                  | 86*                       |
| 52•3                  | CISLUNAR NAVIGATION STAR/LUNAR HORIZON ORIENT | 63691.       | .8                      | 1160.4                  | 86.                       |
| 52+3                  | MIN. IMPULSE MARKING                          | 63691.       | . 4                     | 1160+1                  | 86.                       |
| 52+3                  | NAV SIGHTING SET Z                            | 63690,       | .8                      | 1159+3                  | 86.                       |
| 52•3                  | MINIMUM IMPULSE MARKING                       | 63690.       | . 4                     | 1158+9                  | 86.                       |
| 52+3                  | NAV SIGHTING SET 3                            | 63689.       | . 5                     | 1158+1                  | 86.                       |
| 52 • 3                | MINIMUM IMPULSE MARKING                       | 63688.       | . 4                     | 1157.7                  | 86.                       |
| 52•3                  | NAV SIGHTING SET 4                            | 63687.       | . 8                     | 1156.9                  | 86.                       |
| 52•3                  | MINIMUM IMPULSE MARKING                       | 63487.       | . 4                     | 1156.4                  | 86.                       |
| 52•3                  | NAV SIGHTING SET 5                            | 63686.       | .8                      | 1155-6                  | 84.                       |
| 52 • 3                | MINIMUM IMPULSE MARKING                       | 63686.       | . 4                     | 1155+2                  | 86.                       |
| 53•3                  | ORIENT FOR PTC<br>3AXIS 0.2 DEG/SEC           | 63685.       | .8                      | 1154.4                  | 86.                       |
| 53+3                  | ATTITUDE HOLD 0.5 DEG DB PGNCS                | 63684.       | .8                      | 1153+6                  | 86                        |
| 53+3                  | 'EST. D.3 DEG/SEC ROLL                        | 43684.       | • 2                     | 1153•4                  | 86.                       |
| 53•3                  | PITCH AND YAW CUNTROL                         | 63675.       | 6.8                     | 1144.4                  | 85.                       |

| ,            | SM-RCS PROPELLANT BU                     | DGET            | <b></b>                 |                         |                           |
|--------------|--|-----------------|-------------------------|-------------------------|---------------------------|
| TIME<br>(BR) | EVENT                                    | S/C WT<br>(LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 60.0         | PS2 IMU ALIGN                            | 63674.          | . 9                     | 1143+7                  | 85.                       |
| ≈60°5        | MIDCOURSE CORRECTION 3 AXIS ORIENT PGNCS | 63673.          | .9                      | 1142•7                  | 85.                       |
| 60•5         | ATT HOLD 0.5 DEG DB PGNCS                | 63673.          | . 4.                    | 1142+4                  | 85.                       |
| v 61 • 0     | RCS -X TRANS PGNCS 7 FPS                 | 63622.          | 51.2                    | 1091 • 2                | 81•                       |
| 61 • 2       | ORIENT FOR PTC<br>BAXIS 0.2 DEG/SEC      | 63621.          | .8                      | 1090.4                  | 81.                       |
| 61 • 2       | ATTITUDE HOLD D.5 DEG DB PGNCS           | 63620.          | .8                      | 1089.4                  | 81.                       |
| 61 • 2       | EST. 0.3 DEG/SEC ROLL                    | 63620.          | .3                      | 1089-3                  | 81.                       |
| 61 • 2       | PITCH AND YAW CONTROL                    | 63612.          | 7.5                     | 1081.4                  | 80.                       |
| 66•0         | P52 IMU ALIGN                            | 63612.          | . 9                     | 1080.9                  | 80.                       |
| 66.5         | ORIENT FOR PTC<br>3AXIS 0.2 DEG/SEC      | 63611.          | .8                      | 1080.2                  | 80.                       |
| 66•5         | ATTITUDE HOLD 0.2 DEG DB                 | 63610.          | .8                      | 1079•4                  | 80.                       |
| 66•5         | EST. D.3 DEG/SEC ROLL                    | 63610.          | .3                      | 1079.1                  | 80.                       |
| 66.5         | PITCH AND YAW CUNTROL                    | 63609.          | . 5                     | 1078 • 6                | 80.                       |
| 67•0         | MANEUVER TO LOI1 ATT                     | 63608,          | .8                      | 1077.A                  | 80 •                      |
| 67•1         | ORIENT FOR PTC<br>3AXIS D.2 DEG/SEC      | 63608.          | . 8                     | 1077 • 1                | 80.                       |

|              | 5M-RCS PROPELLANT BUR                            | SET             |                         |                         |                            |
|--------------|--|-----------------|-------------------------|-------------------------|----------------------------|
| TIME<br>(HR) | EVENT  | S/C wT<br>(LB5) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM =<br>RCS<br>LEFT<br>(%) |
| 67 • 1       | ATT HOLD .5 DEG DB PGNC5                         | 63607.          | . 8                     | 1076•3                  | 80.                        |
| 67 • 1       | EST• U•3 DEG/SEC ROLL                            | 63607.          | <sub>*</sub> 2          | 1076-1                  | 80.                        |
| 67 • 1       | PITCH AND YAW CONTROL                            | 63605.          | 1.3                     | 1074•я                  | 80.                        |
| 68.2         | P52 IMU ALIGN                                    | 63604.          | , 9                     | 1073.9                  | 80.                        |
| 168.4        | LUNAR ORBIT INSERTION BURN 1 3-AXIS ORIENT PONCS | 63604.          | . 9                     | 1073.0                  | 80•                        |
| 68.4         | AIT HOLD .5 DEG DB PGNCS                         | 63603.          | • 4                     | 1072+6                  | ឧប្-                       |
| 68 • 4       | START TRANSIENT CONTROL<br>NO ULLAGE             | 63602.          | 1.3                     | 1071.3                  | 79.                        |
| 69+1         | SPS BURN<br>BUILDUP                              | 63599.          | <b>.</b> ⊔              | 1071 • 3                | 79.                        |
| 69+1         | STEADY STATE BURN 245.8 SEC PGN                  | 47037.          | . 3                     | 1070.9                  | 79.                        |
| 69.1         | TAILOFF  | 46996.          | • 0                     | 1070.9                  | 79.                        |
| 69•1         | DAMP SHUT DOWN TRANSIENT                         | 46995,          | 1 • 1                   | 1U69•8                  | 79.                        |
| 69.1         | ATTITUDE HOLD 5 DEG DB                           | 46993.          | 2.1                     | 1067.7                  | 79.                        |
| 69 • 5       | ROLL 180 DEG                                     | 46992.          | l. Ü                    | 1066.7                  | 79.                        |
| 69.5         | ATTITUDE HOLD 5 DEG DB                           | 4699ዐ•          | 2 • 1                   | 1064.5                  | 79.                        |
| 70.3         | P52 IMU ALIGN                                    | 46989.          | . B                     | 1063.7                  | 79.                        |

|           | SM-RCS PROPELLANT BUD                       | GET             |                         | 1                       |                           |
|-----------|---|-----------------|-------------------------|-------------------------|---------------------------|
| TIME (HR) | EVENT                                       | S/C WT<br>(Las) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 70+6      | ORIENT TO TRACKING ATTITUDE PITCH ID ORDEAL | 46988.          | 1 * 1                   | 1062.6                  | 79.                       |
| 70+6      | EST ORBITAL RATE                            | 46986.          | 1.5                     | 1061-1                  | 79.                       |
| 71 • 1    | MAINTAIN ORB RATE AND COAS GRUUND TRACK     | 46786.          | • 7                     | 1060.4                  | 79•                       |
| 71 • 3    | COAS GROUND TRACK DETERMINATION             | 46985.          | . 7                     | 1059.7                  | 79.                       |
| 71.5      | YAW 45 DEG RT FOR TV ORDEAL                 | 46982.          | 2.9                     | 1056-я                  | 78•                       |
| 71 • 6    | YAW 45 DEG LEFT                             | 46979.          | 2.9                     | 1053.9                  | 78•                       |
| 71•9      | ORIENT FOR PSEUDO LANDING                   | 46978,          | 1.1                     | 1052.7                  | 78.                       |
| 72 • 0    | MAINTAIN ORB RATE AND COAS GROUND TRACK     | 46977.          | • 7                     | 1052•n                  | 7g.                       |
| 72•4      | PITCH •2 DEG/SEC TO BURN ATT                | 46977.          | . 3                     | 1051.7                  | 78•                       |
| 72•5      | ATTITUDE HOLD 5 DEG DB                      | 46973.          | 4.3                     | 1047•4                  | 78•                       |
| 72.6      | PS2 IMU ALIGN                               | 46972.          | . 8                     | 1046•6                  | 78•                       |
| 73+0      | ROLL LEFT 180 DEG 20EG/SEC                  | 46971           | 1.0                     | 1045.4                  | 78.                       |
| 73•0      | ATTITUDE HOLD U.2 DEG DB                    | 46970.          | . 8                     | 1044•A                  | 78•                       |
| V 73.5    | LUNAR ORBIT INSERTION BURN 2 ORIENTATION    | 46969.          | .8                      | 104#+n                  | 77•                       |
| 73.5      | ATT HOLD .5 DEG DB PONCS                    | 46968.          | 1 = 1                   | 1042.9                  | 77.                       |

|                          | SM-RCS PROPELLANT BU:           | GET             | ·                       |                         | 2,0                       |
|--------------------------|---------------------------------|-----------------|-------------------------|-------------------------|---------------------------|
| T <sub>IME</sub><br>(HR) | EAEN1                           | S/C WT<br>(L85) | SM+RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 73•5                     | ULLAGE<br>2 JET 8 AND D         | 46952+          | 15.7                    | 1027 • 2                | 76•                       |
| 73+5                     | SPS BURN<br>BUILD UP            | 46949.          | .0                      | 1027.2                  | 76•                       |
| 73•5                     | STEADY STATE BURN 9.7 SEC PGNCS | 46296.          | • 2                     | 1027•0                  | 76.                       |
| 73•5                     | TAILOFF                         | 46255.          | •0                      | 1027•n                  | 76.                       |
| 73•5                     | DAMP SHUT DOWN TRANSIENT        | 46254.          | 1.1                     | 1025.9                  | 76.                       |
| 73.7                     | ROLL RIGHT 180 DEG              | 46253.          | 1-1                     | 1024•A                  | 76•                       |
| 73.8                     | ORIENT TO TRACKING ATTITUDE     | 46252.          | 1 • 1                   | 1023.7                  | 76.                       |
| 73•8                     | EST ORBITAL RATE                | 46250.          | 1.5                     | 1022 • 2                | 76.                       |
| 74•1                     | ORIENT FOR LANDMARKS            | 46249.          | 1.1                     | 1021.2                  | 76.                       |
| 74+3                     | PITCH TO ACQUIRE MSFN           | 46248.          | 1.3                     | 1019.9                  | 76.                       |
| 74+3                     | ATTITUDE HOLD 5 DEG 08          | 46246.          | 2.1                     | 1017.7                  | 76.                       |
| 74+5                     | P52 IMU ALIGN                   | 46245.          | . 8                     | 1016.9                  | 75.                       |
| 75 • 0                   | PITCH TO VERTICAL .2 DEG/SEC    | 46244.          | .7                      | 1016+2                  | 75•                       |
| 75 • 2                   | . ROLL 180 DEG                  | 46244.          | . 3                     | 1015.9                  | 75.                       |
| 75•2                     | EST ORBITAL RATE                | 46243.          | 1.5                     | 1014 • 4                | 75.                       |

|           | SM-RCS PROPELLANT BUD                               | GET    |                         |               |                           |
|-----------|---|--------|-------------------------|---------------|---------------------------|
| TIME (HR) | EVENT   | (L8S)  | SM=RCS<br>USED<br>(LBS) | LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 75.7      | ROLL RIGHT 180 DEG 2 DEG/SEC                        | 45241. | 1.1                     | 1013+3        | 75.                       |
| 75 • 8    | MAINTAIN ORB RAIE                                   | 46240. | 1.5                     | 1011•8        | 75+                       |
| 76•U      | ORIENT FOR LANDMARKS, PHOTOGRAPHY                   | 46239. | 1.1                     | 1010+7        | 75•                       |
| 76+1      | EST AND STOP SIGHTING RATE                          | 46238. | 1.3                     | 1009•4        | 75•                       |
| 76•4      | ROLL 180 DEG 2 DEG/SEC                              | 46236. | 1 + 1                   | 1008+3        | 75•                       |
| 76•5      | ATTITUDE HOLD 5 DEG DB                              | 46236. | .4                      | 1007.9        | 75.                       |
| 76 • 6    | P52 IMU ALIGN                                       | 46235. | . 8                     | 1007+1        | 75.                       |
| 77 • 1    | ROLL 180 DEG 2 DEG/SEC                              | 46234. | 1 • 1                   | 1006•n        | 75.                       |
| 77•1      | PITCH DOWN • 2 DEG/SEC                              | 46234. | .4                      | 1005 • 4      | 75,                       |
| 77 • 1    | EST. ORB RATE                                       | 46232. | 1.5                     | 1004•1        | 75.                       |
| 77.2      | CONTROL POINT SIGHTING                              | 46231. | 1.1                     | 1003•r        | 74.                       |
| 77•3      | PITCH +3 DEG/SEC AT ACO                             | 46231. | • 5                     | 1002 • 4      | 74.                       |
| 77.7      | PITCH .2 DEG/SEC AT LOSS                            | 46230  | 7                       | 7 1001 • 9    | 74.                       |
| 77 • 7    | EST. ORB RATE                                       | 46229  | 1.5                     | 1000.4        | 74.                       |
| 78•0      | ORIENT FOR PSEUDO LANDING SITE<br>LANDMARK SIGHTING | 46227  | .   1.                  | 1 999•        | 74.                       |

| <del></del>  | SH-RCS PROPELLANT                                  | BUNGET          | ·                       |                         | _                 |
|--------------|--|-----------------|-------------------------|-------------------------|-------------------|
| TIME<br>(HR) | EVENÍ  | S/C WT<br>(LBS) | SMTRCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>UEF |
| 78•0         | PITCH .3 DEG/SEC AT ACO                            | 46227.          | • 5                     | 998.9                   | 74                |
| 78•3         | ROLL 180 DEG AT LOSS                               | 46226.          | 1 - 1                   | 997•B                   | 74                |
| 78•5         | ATTITUDE HOLD 5 DEG DB                             | 46224.          | 2.1                     | 995•4                   | 74                |
| 78•6         | PS2 IMU ALIGN                                      | 46223.          | . 8                     | 994.A                   | 74                |
| 79.0         | BOLF 180 DEC                                       | 46222.          | 1 a I                   | 993•д                   | 74                |
| 79 • 1       | PITCH 2 DEG/SEC                                    | 46219.          | 2.4                     | 991 • 3                 | 74                |
| 79.1         | EST. ORB RATE                                      | 46218.          | 1.5                     | 989.д                   | 7.3               |
| 79.1         | CONTROL POINT SIGHTING                             | 46217.          | 1 • 1                   | 988.7                   | 73                |
| 79 • 1       | MAINTAIN SIGHTING RATE                             | 46217.          | . :                     | 988.6                   | 73                |
| 79.5         | PITCH +3 DEG/SEC AT ACQ                            | 46216.          | .5                      | 988.1                   | 73                |
| 79.5         | PITCH .2 DEG/SEC AT LOSS                           | 46216.          | . 3                     | 987+8                   | 73                |
| 79•5         | EST. ORB RATE                                      | 46214.          | 1.5                     | 986+3                   | 73.               |
| 0 • 0 8      | RIENT FOR PSEUDO LANDING SITE<br>LANDMARK SIGHTING | 46213,          | 1.1                     | 985.2                   | 73.               |
| 30.1         | PITCH +3 DEG/SEC AT ACO                            | 46213.          | . 5                     | 984 • 7                 | 73.               |
| 30 • 2       | ROLL 180 DEG AT LOSS                               | 46212.          | 1.1                     | 983.7                   | 73.               |

|           | SM-RCS PROPELLANT BU                             | DGET      |                         | 1 1                     |                           |
|-----------|--|-----------|-------------------------|-------------------------|---------------------------|
| TIME (HR) | EVENT  | S/C WT    | SM±RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SH-<br>RCS<br>LEFT<br>(%) |
| 80 • 2    | ATTITUDE HOLD 5 DEG DB                           | 46210.    | 2 ± 1                   | 981.5                   | 73.                       |
| 80 • 6    | P52 IMU ALIGN                                    | 46209+    | 8                       | 980 • 7                 | 73•                       |
| 80 • 7    | ROLL 180 DEG 2 DEG/SEC                           | 46208.    | 1 • 1                   | 979.6                   | 73•                       |
| 80•8      | PITCH •2 DEG/SEC                                 | 46207.    | .3                      | 979+3                   | 73•                       |
| 80•8      | EST. ORB RATE                                    | 46206.    | 1.5                     | 977 + A                 | 73                        |
| 81+1      | PITCH •3 DEG/SEC AT ACQ                          | 46205     | , 5                     | 977 • 3                 | 73                        |
| 81•3      | PITCH .5 DEG/SEC AT LOSS                         | 46205     | .7                      | 976.4                   | 72                        |
| 81 • 5    | PITCH -3 DEG/SEC AT ACQ                          | 46204     | , 4                     | 976 • 1                 | 7 2                       |
| 81+6      | PITCH .5 DEG/SEC AT LOSS                         | 46204     | . 7                     | 7. 975.+4               | 7 2                       |
| 81 • 7    | PITCH .3 DEG/SEC AT ACQ                          | 46203     | • •                     | 975+[                   | 7 2                       |
| 81+8      | PITCH .5 DEG/SEC AT LOSS                         | 46202     |                         | 7 974.                  | 7 2                       |
| B1 • 9    | ORIENT FOR PSEUDO LANDING SITE LANDMARK SIGHTING | 4.6 2 0 1 | . 1.                    | 1 973.                  | 7 7 2                     |
| 82•1      | PITCH •3 DEG/SEC AT ACN                          | 46201     | •                       | 5 972.                  | 7 72                      |
| 82.3      | ROLL 180 DEG 2 DEG/SEC                           | 46200     |                         | 1 ,971•                 | 6 7:                      |
| 82+3      | ATTITUDE HOLD 5 DEG DB                           | 46195     | 4.                      | 3 967.                  | 3 7                       |

|              | SM-RCS PROPELLANT BU                             | DGET   |                         |                         |                   |
|--------------|--|--------|-------------------------|-------------------------|-------------------|
| TIME<br>(HR) | EVENT  | S/C HI | SM_RCS<br>USED<br>(LBS) | SM_RCS<br>LEFT<br>(LBS) | SM_<br>RCS<br>LEF |
| 82•5         | PS2 IMU ALIGN                                    | 46195* | .8                      | 966.5                   | 72                |
| 82•8         | ROLL 180 DEG 2 DEG/SEC                           | 46194. | 1 - 1                   | 965.5                   | 72.               |
| 83.0         | PITCH .2 DEG/SEC                                 | 46193. | . 3                     | 965•1                   | 72.               |
| 83+1         | PITCH .3 DEG/SEC AT ACO                          | 46193. | • 5                     | 964.7                   | 72.               |
| 83+3         | PITCH .S DEG/SEC AT LOSS                         | 46192. | • 7                     | 964.0                   | 72.               |
| 83 • 4       | PITCH +3DEG/SEC                                  | 46192. | .5                      | 963.5                   | 71.               |
| 83 • 6       | PITCH .5 DEG/SEC                                 | 46191. | . 7                     | 962 • A                 | 71•               |
| 83•7         | PITCH .3DEG/SEC                                  | 46191. | #S                      | 962.4                   | 7;•               |
| 83 • 8       | PITCH +5 DEG/SEC                                 | 46190. | . 7                     | 961.7                   | 71.               |
| 83•9         | ORIENT FOR PSEUDO LANDING SITE LANDMARK SIGHTING | 46189. | 1 - 1                   | 900+5                   | 71.               |
| 84 • 2       | PITCH .3DEG/SEC                                  | 46188. | . 5                     | 960+1                   | 71.               |
| 84 • 2       | ROLL 180 DEG 2 DEG/SEC                           | 46187. | 1.0                     | 959 • n                 | 71.               |
| 84•2         | ATTITUDE HOLD 5 DEG DB                           | 46185. | 2 • 1                   | 956.0                   | 7 t •             |
| 84.5         | PSZ IMU ALIGN                                    | 96184. | . B                     | 956+1                   | 71.               |
| 84.7         | PITCH .2 DEG/SEC                                 | 46184. | . 3                     | 955.7                   | 71.               |

|                   | SM-RCS PROPELLANT-B               | UNGET           |                         | 1                       |                           |
|-------------------|-----------------------------------|-----------------|-------------------------|-------------------------|---------------------------|
| TIME (HR)         | EVENT                             | S/C WT<br>(LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM=<br>RCS<br>LEFT<br>(%) |
| 84 • 7            | ESTABLISH ORB RATE                | 46182*          | 1.5                     | 954+2                   | 71*                       |
| 85+1              | PITCH UP 70 DEG AT .5 DEG/SEC     | 46182.          | . 7                     | 953.5                   | 71•                       |
| 85 • 1            | MAINTAIN ORB RATE                 | 46182.          | .1                      | 953+4                   | 71.                       |
| 85•5              | PITCH UP 40 DEG AT .2 DEG/SEC     | 46181.          | , 3                     | 953.0                   | 71.                       |
| 85•7              | ROLL 180 DEG                      | 46180.          | 1.0                     | 952•n                   | 71.                       |
| 86 * 2            | ROLL 180 DEG ZDĽĠ/SEC             | 46179.          | 1 • 1                   | 950.0                   | 71.                       |
| 86•3              | PITCH 60DEG .2DEG/SEC .           | 46179.          | . 3                     | 950 • A                 | 71.                       |
| 86•2              | ATTITUDE HOLD 5 DEG DB            | 46177.          | 2.1                     | 948 • 5                 | 70+                       |
| 86+7 <sup>-</sup> | P52 IMU ALIGN                     | 46176.          | .8                      | 947.7                   | 70.                       |
| 86•9              | PITCH +2 DEG/SEC                  | 46175.          | * 3                     | 947•3                   | 70.                       |
| 86•9              | ESTABLISH ORB RATE                | 46174.          | 1.5                     | 945.8                   | 7 ü •                     |
| 88+3              | P52 IMU ALIGN                     | 46173.          | . 8                     | 945•1                   | 70•                       |
| 88•7              | ROLL 18D DEG                      | 46173.          | . 3                     | 944+7                   | 70•                       |
| 89 • 1            | TRANS-EARTH INJECTION ORIENTATION | 46172.          | 3.                      | 943.4                   | 70.                       |
| 89 • 1            | ATT HOLD .5 DEG DB                | 46171.          | 1.1                     | 942.9                   | 70.                       |

|              | SM-RCS PROPELLANT BU                             | DGET   |                         |                         |                   |
|--------------|--|--------|-------------------------|-------------------------|-------------------|
| TIME<br>(HR) | EVENT  | S/C WT | SM-RCS<br>USED<br>(L85) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEF |
| 89 • 1       | ULLAGE 2 JET B AND D QUADS 21 SEC PGNCS          | 46155. | 15.7                    | 927 • 1                 | 69                |
| 89•1         | SPS BURN<br>BUILD UP                             | 46152. | .0                      | 927 • [                 | 69.               |
| 89 * 1       | STEADY STATE BURN 206 SEC PGNCS                  | 32272. | . 2                     | 926.9                   | 69.               |
| 89+1         | TAILOFF  | 32231. | • 0                     | 926 * 9                 | 69.               |
| 89•1         | DAMP SHUT DOWN TRANSIENT                         | 32230. | 1 • 1                   | 925•8                   | 69.               |
| 89+2         | PITCH TO VERTICAL<br>ACQUIRE MOON                | 32229. | • 7                     | 925•1                   | 69.               |
| 90 • 2       | P52 IMU ALIGN                                    | 32229. | • 7                     | 924*4                   | 69.               |
| 90.5         | CISLUNAR NAVIGATION<br>STAR/LUNAR HORIZON ORIENT | 32228. | 1.0                     | 923.4                   | 69.               |
| 90•5         | MIN. IMPULSE MARKING                             | 32227. | <b>.</b> 4              | 923•n                   | 68.               |
| 90•5         | NAV SIGHTING SET 2                               | 32226. | 1.0                     | 922•0                   | 68.               |
| 90.5         | MINIMUM IMPULSE MARKING                          | 32226. | , <del>1</del>          | 921.4                   | 68.               |
| 90+5         | NAV SIGHTING SET 3                               | 32225. | 1.0                     | 920.4                   | 68.               |
| 90•5         | MINIMUM IMPULSE MARKING                          | 32225. | , 4                     | 920+2                   | 68.               |
| 91.0         | NAV SIGHTING SET 4                               | 32224. | 1.0                     | 919+2                   | 68.               |
| 91.0         | MINIMUM IMPULSE MARKING                          | 32223. | . 4                     | 918 • 8                 | 68.               |

|              | SM-RCS PROPELLANT BUD               | GET             |      |                         |                       |
|--------------|-------------------------------------|-----------------|------|-------------------------|-----------------------|
| TIME<br>(HR) | EVENT                               | S/C WT<br>(LBS) | USED | SM-RCS<br>LEFT<br>(LBS) | SM-RCS<br>LEFT<br>(%) |
| 91.0         | NAV SIGHTING SET 5                  | 32222+          | 9    | 917.9                   | 68.                   |
| 91.0         | MINIMUM IMPULSE MARKING             | 32222.          | .4   | 917+4                   | 48.                   |
| 91•0         | NAV SIGHTING SET 6                  | 32221•          | 1.0  | 916+5                   | 68.                   |
| 91•0         | MINIMUM IMPULSE MARKING             | 32220.          | . 4  | 916+n                   | 68.                   |
| 91•0         | NAV SIGHTING SET 7                  | 32219.          | 1.0  | 915-1                   | 68 •                  |
| 91.0         | MINIMUM IMPULSE MARKING             | 32219.          | .4   | 914•6                   | 68.                   |
| 91+0         | NAV SIGHTING SET 8                  | 32218.          | 1.0  | 913.7                   | 68.                   |
| 91•0         | MINIMUM IMPULSE MARKING             | 32218.          | . 4  | 913+2                   | 68.                   |
| 92•0         | ORIENT FOR PTC (YAW TEST)           | 32217+          | .7   | 912+5                   | 68                    |
| 92•0         | ATT HOLD .5 DEG DB PGNCS            | 32216.          | .8   | 911+7                   | 68                    |
| 92+0         | EST. D.3 DEG/SEC YAW                | 32216.          | . 5  | 911+3                   | 68                    |
| 9 2 • Ü      | PITCH AND ROLL CONTROL              | 32210.          | 5.6  | 905 • 7                 | 67                    |
| 96•0         | P52 IMU ALIGN                       | 32209.          | • 7  | 905.0                   | 67                    |
| 96+3         | ORIENT FOR PTC<br>3AX15 0.2 DEG/SEC | 32209.          | • 7  | 904+3                   | 67                    |
| 96•3         | ATTITUDE HOLD O.S DEG DB PGNCS      | 32208.          | .8   | 903+5                   | 67                    |

| JIME   | EVENT  | S/C WT | Su=000        | SM-RCS        | e .                      |
|--------|--|--------|---------------|---------------|--------------------------|
| (HR)   |  | (L65)  | USED<br>(LBS) | LEFT<br>(LBS) | SM-<br>RCS<br>LEF<br>(%) |
| 96•3   | , and organized Rock                             | 32208. | • 2           | 903.3         | 67                       |
| 96•3   | PITCH AND YAW CONTROL                            | 32202. | 5.2           | 898*1         | 67                       |
| 100.0  | PSZ IMU ALIGN                                    | 32202. | • 7           | 897.4         | 67                       |
| 100+5  | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 32201. | 1.0           | 896.4         | 67                       |
| 100.5  | MIN. IMPULSE MARKING                             | 32200. | • 4           | 896•0         | 66.                      |
| 100.5  | NAV SIGHTING SET 2                               | 32199. | 1.0           | 895•n         | 66.                      |
| 00•5   | MINIMUM IMPULSE MARKING                          | 32199. | . 4           | 894.4         | 66.                      |
| 00+5   | NAV SIGHTING SET 3                               | 32198. | 1.0           | 893.4         | 66.                      |
| 00+5,  | MINIMUM IMPULSE MARKING                          | 32198. | u 4           | 893+2         | 66.                      |
| 01.0   | MAN TO SIGHTING ATT                              | 32197. | 1 . 0         | 892.2         | 66,                      |
| 01.5   | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 32146. | . 9           | 891+3         | 66•                      |
| 01 • 5 | MIN. IMPULSE MARKING                             | 32195. | . 4           | 890•A         | 66.                      |
| 01.5   | NAV SIGHTING SET 2                               | 32194. | 1.0           | 889.9         | 66.                      |
| 01.5   | MINIMUM IMPULSE MARKING                          | 32194. | . 4           | 887.4         | 66.                      |
| 01.5   | NAV SIGHTING SET 3                               | 32193. | 1.0           | 888.4         | 66.                      |

|              | SM-RCS, PROPELLANT BUD                           | GET             |                         |                         |                           |
|--------------|--|-----------------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  | S/C WT<br>(LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 101+5        | MINIMUM IMPULSE MARKING                          | 32192.          | . 4                     | 888•n                   | 66.                       |
| 101+5        | NAV SIGHTING SET 4                               | 32191.          | 1.0                     | 887.1                   | 66•                       |
| 101.5        | MININUM INPULSE MARKING                          | 32191.          | . 4                     | 886+6                   | 66*                       |
| 102.0        | NAV SIGHTING SET 5                               | 32190.          | 1.0                     | 885.7                   | 66.                       |
| 102+0        | MIN. IMPULSE MARKING                             | 32190.          | .4                      | 885 . 2                 | 66.                       |
| 102+0        | NAV SIGHTING SET 6                               | 32189.          | 1.0                     | 884.3                   | 66.                       |
| 102.0        | MINIMUM IMPULSE WARKING                          | 32188.          | 4                       | 883.9                   | 66,                       |
| 102•8        | P52 IMU ALIGN                                    | 32188.          | .7                      | 883*1                   | 66.                       |
| 103.5        | MIDCOURSE CORRECTION                             | 32187.          | 1.0                     | 882.2                   | 65.                       |
| 103.5        | ATTITUDE HOLD .5 DEG DB PGNCS                    | 32186.          | .8                      | 881.4                   | 65.                       |
| 103.5        | RCS +X TRANS PGNCS 10 FPS                        | 32149.          | 37.1                    | 844.3                   | 63.                       |
| 105+0        | P52 INU ALIGN                                    | 32148.          | . 7                     | 843.4                   | 63.                       |
| 105+2        | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 32147.          | 1 • .0                  | 842.6                   | 63.                       |
| 105+2        | MIN. IMPULSE MARKING                             | 32147.          | . 4                     | 842.2                   | 62.                       |
| 105 • 2      | NAV SIGHTING SET 2                               | 32146.          | 1.0                     | 841.2                   | 62.                       |

|              | SH_RCS PROPELLANT                                | BUNGET          | <del></del>             | <b>.</b>                | - <del></del> -           |
|--------------|--|-----------------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  | S/C WT<br>(LBS) | SM_RCS<br>USED<br>(LBS) | SM_RCS<br>LEFT<br>(LBS) | SM_<br>RCS<br>LEFT<br>(%) |
| 105 • 2      | MINIMUM IMPULSE MARKING                          | 32145.          | . 4                     | 840.7                   | 62.                       |
| 105 • 2      | NAV SIGHTING SET 3                               | 32144.          | 1.0                     | 839*A                   | 62.                       |
| 105•2        | MINIMUM IMPULSE MARKING                          | 32144.          | . 4                     | 839.3                   | 62.                       |
| 105+2        | NAV SIGHTING SET 4 .                             | 32143.          | 1 • 0                   | 838•4                   | 62•                       |
| 105•2        | MINIMUM IMPULSE MARKING                          | 32142.          | . 4                     | 837.9                   | 62.                       |
| 105.2        | NAV SIGHTING SET 5                               | 32141.          | 1.0                     | 837 • n                 | 62.                       |
| 105+2        | MINIMUM IMPULSE MARKING                          | 32141.          | . 4                     | 836•4                   | 62.                       |
| 106+1        | MAN TO SIGHTING ATT                              | 32140.          | 1.0                     | 835+6                   | 62•                       |
| 106.3        | CISLUNAR NAVIGATION<br>STAR/LUNAR HORIZON GRIENT | 32139.          | 1.0                     | 834+6                   | 62•                       |
| 106+3        | MIN. IMPULSE MARKING                             | 32139.          | . 4                     | 834.1                   | 62.                       |
| 106+3        | NAV SIGHTING SET 2                               | 32138.          | 1.0                     | 833.2                   | 62.                       |
| 106 - 3      | MINIMUM IMPULSE MARKING                          | 32137.          | <b>,</b> 4              | 832.7                   | 62.                       |
| 106.13       | NAV SIGHTING SET 3                               | 32136.          | 1.0                     | R • 1 E 8               | 62.                       |
| 106.3        | MINIMUM IMPULSE MARKING                          | 32136.          | . 4                     | 831.3                   | 62.                       |
| 107+6 F      | 52 IMU ALIGN                                     | 32135.          | • 7                     | 830.4                   | 62.                       |

|           | SM-RCS PROPELLANT                                | BUDGET |                         | <del> </del>            | ·                         |
|-----------|--|--------|-------------------------|-------------------------|---------------------------|
| TIME (HR) | EVENT  | (LBS)  | SMTRCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM=<br>RCS<br>LEFT<br>(%) |
| 108+0     | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 32134. | 1.0                     | 829.7                   | 62.                       |
| 108+0     | MIN. IMPULSE MARKING                             | 32134. | • 4                     | 829+2                   | 62.                       |
| 108+0     | NAV SIGHTING SET 2                               | 32133. | 1.0                     | 828+3                   | 61.                       |
| 108.0     | MINIMUM IMPULSE MARKING                          | 32132. | Ťđ                      | 827 + R                 | 61.                       |
| 108.0     | NAV SIGHTING SET 3                               | 32131. | 1.0                     | 826.9                   | 61.                       |
| 108.0     | MININUM IMPULSE MARKING                          | 32131+ | • 4                     | 826 • 4                 | 61.                       |
| 108+0     | NAV SIGHTING SET 4                               | 32130. | 1,0                     | 825.5                   | 61.                       |
| 108.0     | MINIMUM IMPULSE MARKING                          | 32129. | • 4                     | 825 • 0                 | 61.                       |
| 108.0     | NAV SIGHTING SET 5                               | 32128. | 1.0                     | 824 • 0                 | 61.                       |
| 108+0     | MINIMUM IMPULSE MARKING                          | 32128. | . 4                     | 823.4                   | 61                        |
| 108 • 8   | ORIENT FOR PTC<br>BAXIS D.2 DEG/SEC              | 32127. | .7                      | 822 • 9                 | 61                        |
| 108+8     | ATT HOLD .S DEG DB PGNCS                         | 32127. | .8                      | 822 • 2                 | 61                        |
| 108.8     | EST. 0.3 DEG/SEC ROLL                            | 32126. | ± 4                     | 821.7                   | 61                        |
| 108 • 8   | PITCH AND YAW CONTROL                            | 32120. | 6.0                     | 815.7                   | 61                        |
| 113 + 0   | ORIENT FOR PTC<br>3AXIS U.Z DEG/SEC              | 32119. | • 7                     | 815 • 0                 | 60                        |

| SM-RCS PROPELLANT BUDGET |  |            |                         |                         |                    |  |  |
|--------------------------|--|------------|-------------------------|-------------------------|--------------------|--|--|
| TIME<br>(HR)             | EVENT  | S/C WT     | SM_RCS<br>USED<br>(L85) | SM_RCS<br>LEET<br>(LBS) | SM_<br>RCS<br>LEFT |  |  |
| 113.0                    | ATTITUDE HOLD 0.5 DEG DB PG                      | NCS 32119. | . 8                     | 814.3                   | 60.                |  |  |
| 113+0                    | EST. D.3 DEG/SEC ROLL                            | 32118,     | . 2                     | 814+1                   | 60.                |  |  |
| 1                        | PITCH AND YAW CONTROL                            | 32116.     | 2,8                     | 811+3                   | 60.                |  |  |
| 1]5.]                    | P52 IMU ALIGN                                    | 32115.     | . 7                     | 810.6                   | 60.                |  |  |
| 115+3                    | ORIENT FOR PIC<br>BAXIS D.2 DEG/SEC              | 32114.     | 7                       | 809.9                   | 60.                |  |  |
| 115+3                    | ATTITUDE HOLD D.S DEG DB PG                      | NCS 32113. | ., 8                    | 809•1                   | àQ.                |  |  |
| l 15 • 3                 | EST. (1.3 DEG/SEC ROLL                           | 32113.     | , 2                     | 808+9                   | 60.                |  |  |
| 115•3                    | PITCH AND YAM CONTROL                            | 32108,     | 5.0                     | 803.9                   | 60.                |  |  |
| l 19•0                   | URIENT FOR PTC<br>BAXIS 0.2 DEG/SEC              | 32108.     | , 7                     | 803.2                   | 4D.                |  |  |
| 119.0                    | ATT HOLD .5 DEG DB PGNCS                         | 32107.     | , 8                     | 802+5                   | 60.                |  |  |
| 119•8                    | EST. 0.3 DEG/SEC ROLL                            | 32107.     | . 2                     | 802+3                   | 60.                |  |  |
| 119+0                    | PITCH AND YAW CUNTROL                            | 32105.     | 1 • 4                   | 800+9<br>:              | 59.                |  |  |
| 20 • 0                   | P52 IMU ALIGN                                    | 32105.     | .7                      | 800+2                   | 59•                |  |  |
| 20.0                     | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | -32104.    | 1.0                     | 799+2                   | 59.                |  |  |
| 20.0                     | MIN. IMPULSE MARKING                             | 32103.     | . 4                     | 798 + д                 | 59.                |  |  |

|              | SM-RCS PROPELLANT BU                             | nGET            | <del> :-</del> |               |                    |
|--------------|--|-----------------|----------------|---------------|--------------------|
| TIME<br>(HR) | EVENT  | S/C WT<br>(LBS) | USED           | LEFT<br>(LBS) | SM-<br>RCS<br>LEFT |
| 120+0        | NAV SIGHTING SET 2                               | 32102.          | 1.0            | 797•я         | 59.                |
| 120•0        | MINIMUM IMPULSE MARKING                          | 32102.          | . 4            | 797+3         | 59.                |
| 120+0        | NAV SIGHTING SET 3                               | 32101.          | 1,0            | 796+4         | 59.                |
| 120 • 0      | MINIMUM IMPULSE MARKING                          | 32100.          | . 4            | 795.9         | 59.                |
| 121+0        | P52 IMU ALIGN                                    | 32100.          | . 7            | 795+2         | 59•                |
| 121 • 5      | MIDCOURSE CORRECTION 3 AXIS ORIENT PGNCS         | 32049+          | . 7            | 794•5         | 59•                |
| 121•5        | ATT HOLD •5 DEG DB PGNCS                         | 32098.          | .4             | 794 • 1       | 59.                |
| 121+5        | SM-RCS -X TRANS 2FPS                             | 32091.          | 7.5            | 786.6         | 58.                |
| 122.6        | CISLUNAR NAVIGATION<br>STAR/LUNAR HORIZON ORIENT | 32(190.         | 1.0            | 785.6         | 58.                |
| 122+6        | MIN. IMPULSE MARKING                             | 32090.          | . 4            | 785.2         | 58.                |
| 122+6        | NAV SIGHTING SET 2                               | 32089.          | 1.0            | 784.2         | 58*                |
| 122+6        | MINIMUM IMPULSE MARKING                          | 32088.          | . 4            | 783+8         | 58•                |
| 122.6        | NAV SIGHTING SET 3                               | 32087.          | 1.0            | 782•B         | 58.                |
| 122•6        | MINIMUM IMPULSE MARKING                          | 32087           | .4             | 782.4         | 58.                |
| 123 • 1      | MANEUVER TO SIGHTING ATTITUDE                    | 32086           | . 9            | 781 • 5       | 58.                |

|           | SM-RCS PROPELLANT                                | BUDGET       |                         |                         |                           |
|-----------|--|--------------|-------------------------|-------------------------|---------------------------|
| TIME (HR) | EVENT  | S/C WT (LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(L8S) | SM-<br>RCS<br>LEFT<br>(%) |
| 123 • 6   | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 32085.       | 1.0                     | 780+5                   | 58.                       |
| 123+6     | MIN. IMPULSE MARKING                             | 32084.       | . 4                     | 780 • 1                 | 58.                       |
| 123.6     | NAV SIGHTING SET 2                               | 32083*       | 1.0                     | 779.1                   | 58.                       |
| 123.6     | MINIMUM IMPULSE MARKING                          | 32083.       | . 4                     | 778+7                   | 58.                       |
| 123.6     | NAV SIGHTING SET 3                               | 32082.       | 1 • 0                   | 777.7                   | 58.                       |
| 123.6     | MINIMUM IMPULSE MARKING                          | 32082.       | . 4                     | 777.3                   | 58+                       |
| 123.6     | NAV SIGHTING SET 4                               | 32081.       | 1.0                     | 776+3                   | 58•                       |
| 123.6     | MINIMUM IMPULSE MARKING                          | 32080.       | . 4                     | 775+9                   | 58.                       |
| 123 • 6   | NAV SIGHTING SET 5                               | 32079.       | 1.0                     | 774.9                   | 58.                       |
| 123.6     | MINIMUM IMPULSE MARKING                          | 32079.       | . 4                     | 774•5                   | 57.                       |
| 124 • 5   | ORIENT FOR PTC<br>34×15 0+2 DEG/SCC              | 32078.       | . 7                     | 773•a                   | 57•                       |
| 124+5     | ATT HOLD .5 DEG DB PGNCS                         | 32077.       | • B                     | 773·n                   | 57.                       |
| 124.5     | EST. 0.3 DEG/SEC ROLL                            | 32077.       | • 2                     | 772+8                   | 57.                       |
| 124•5     | PITCH AND YAW CONTROL                            | 32070.       | 7.0                     | 765.A                   | 57.                       |
| 129+5     | PS2 IMU ALIGN                                    | 32069.       | . 7                     | 765.1                   | 57.                       |

|              | SM-RCS PROPELLANT B                              | UpGET  |                         |                         |                           |
|--------------|--|--------|-------------------------|-------------------------|---------------------------|
| TIME<br>(HR) | EVENT  |        | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SM-<br>RCS<br>LEFT<br>(%) |
| 130+0        | CISLUNAR NAVIGATION<br>STAR/LUNAR HORIZON ORIENT | 32068. | 1.0                     | 764+1                   | 57.                       |
| 130+0        | MIN. IMPULSE MARKING                             | 32068. | • 4                     | 763+7                   | 57•                       |
| 130.0        | NAV SIGHTING SET 2                               | 32067. | 1.0                     | 762•7                   | 57•                       |
| 130.0        | HINIMUM IMPULSE MARKING                          | 32067. | . 4                     | 762.2                   | 57.                       |
| 130 • 0      | NAV SIGHTING SET 3                               | 32066. | 1.0                     | 761+3                   | 56+                       |
| 130+0        | MINIMUM IMPULSE MARKING                          | 32065. | .4                      | 760.9                   | 56.                       |
| 130+5        | MANEUVER TO SIGHTING ATTITUDE                    | 32064. | 1.0                     | 759•9                   | 56.                       |
| 130+8        | CISLUNAR NAVIGATION<br>STAR EARTH HORIZON ORIENT | 32063. | 1.0                     | 758 • 9                 | 56.                       |
| 130•8        | MINIMUM IMPULSE MARKING                          | 32063. | . 4                     | 758 • 5                 | 56.                       |
| 130 • 8      | NAV SIGHTING SET 2                               | 32062. | 1.0                     | 757.5                   | 56.                       |
| 130.8        | MINIMUM IMPULSE MARKING                          | 32061. | . 4                     | 757+1                   | 56.                       |
| 130.8        | NAV SIGHTING SET 3                               | 32060. | 1.0                     | 756+1                   | 56.                       |
| 130.8        | MINIMUM IMPULSE MARKING                          | 32060. | , 4                     | 755-7                   | 56.                       |
| 131.4        | NAV SIGHTING SET 4                               | 32059. | 1.0                     | 754•7                   | 56.                       |
| 131•4        | MIN. IMPULSE MARKING                             | 32059. | 4                       | 754•3                   | 56.                       |

|              | SM-RC5 PRUPELLANT                   | BUNGET |                         |                         |                    |
|--------------|-------------------------------------|--------|-------------------------|-------------------------|--------------------|
| TIME<br>(HR) | EVENT                               | S/C HT | SM_RCS<br>USED<br>(LBS) | SM_RCS<br>LEFT<br>(LBS) | SH_<br>RCS<br>LEF1 |
| 131•4        | NAV SIGHTING SET 5                  | 32058. | 1.0                     | 753.3                   | 56.                |
| 131+4        | MINIMUM IMPULSE MARKING             | 32057. | . 4                     | 752+8                   | 56.                |
| 131+4        | NAV SIGHTING SET 6                  | 32056. | 1.0                     | 751.9                   | 56.                |
| 131•4        | MINIMUM IMPULSE MARKING             | 32056. | . 4                     | 751+5                   | 56.                |
| 131+8        | ORIENT FOR PTC<br>BAXIS 0.2 DEG/SEC | 32055. | 7                       | 750.7                   | 56.                |
| 131+8        | ATT HOLD .5 DEG DB PGNCS            | 32054. | . 8                     | 749.9                   | 58.                |
| 131+8        | EST. 0.3 DEG/SEC ROLL               | 32054. | n 2                     | 749.7                   | 56.                |
| 31.8         | PITCH AND YAW CONTROL               | 32048. | 6,4                     | 743•3                   | 55.                |
| 135.5        | P52 IMU ALIGN                       | 32047. | . 7                     | 742*A                   | 55.                |
| 135 • 7      | ORIENT FOR PTC<br>3AXIS 0.2 DEG/SEC | 32046. | . 7                     | 741.9                   | 55.                |
| 135•7        | ATT HOLD .5 DEG DB PGNCS            | 32046. | . 8                     | 741 • 1                 | 55.                |
| 35 • 7       | EST. 0.3 DEG/SEC ROLL               | 32045, | • 2                     | 741•n                   | 55.                |
| 35 • 7       | PITCH AND YAW CONTROL               | 32040. | 5 <b>.</b> ü            | 736•n                   | 55•                |
| 39.4         | P52 IMU ALIGN                       | 32040. | • 7                     | 735-2                   | 55+                |
| 39.5         | ORIENT FOR PIC<br>3AXIS 0.2 DEG/SEC | 32039. | . 8                     | 734.5                   | 55.                |

|         | SN-RCS PROPELLANT BU                             | nGET            |                         |                         | <del></del>               |
|---------|--|-----------------|-------------------------|-------------------------|---------------------------|
| TIME    | EVENT  | S/C WT<br>(LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS) | SH-<br>RCS<br>LEFT<br>(%) |
| 139.5   | ATTITUDE HOLD DIS DEG DB RGMCS                   | 32038.          | .8                      | 733.7                   | 54.                       |
| 139.5   | EST. 0.3 DEG/SEC ROLL                            | 32038.          | .2                      | 733.5                   | 54.                       |
| 139•5   | PITCH AND YAW CONTROL                            | 32034.          | 3.9                     | 729.6                   | 54+                       |
| 142 • 2 | CISLUNAR NAVIGATION<br>STAR/EARTH HORIZON ORIENT | 32033.          | 1.0                     | 728+7                   | 54.                       |
| 142•2   | MIN. IMPULSE, MARKING                            | 32033.          | .4                      | 728+2                   | 54.                       |
| 142•2   | NAV SIGHTING SET 2                               | 32032.          | .9                      | 727+3                   | 54.                       |
| 142 • 2 | MINIMUM IMPULSE MARKING                          | 32031.          | .4                      | 726.9                   | 54.                       |
| 143+7   | P52 IMU ALIGN                                    | 32031.          | . 7                     | 726+1                   | 54.                       |
| 144.4   | MIDCOURSE CORRECTION                             | 32030.          | . 7                     | 725 • 4                 | 54.                       |
| 144 = 4 | ATT HOLD .5 DEG DB PGNCS                         | 32030.          | .3                      | 725.2                   | 54,                       |
| 144•4   | RCS +X TRANS PGNCS 5 FPS                         | 32011.          | 18.6                    | 706.                    | 52                        |
| 145•0   | CISLUNAR NAVIGATION STAR EARTH HORIZON ORIENT    | 32011.          | .(                      | 706.                    | 5 2                       |
| 145•0   |  | 32010.          |                         | 706.                    | 5 2                       |
| 145•7   | P52 IMU ALIGN                                    | 32010           | ,                       | 705.4                   | 52                        |
| 146•1   | MANEUVER TO REENTRY ATTITUDE                     | 32009           | . 1 - 5                 | 704.                    | 4 5 Z                     |

| <b></b>      | 5H-RCS PROPELLANT B              | UnGEI           | <del> </del>            | <del>                                     </del> | <del></del>               |
|--------------|----------------------------------|-----------------|-------------------------|--|---------------------------|
| TIME<br>(HR) | EVENT                            | S/C WT<br>(LBS) | SM-RCS<br>USED<br>(LBS) | SM-RCS<br>LEFT<br>(LBS)                          | SM-<br>RCS<br>LEFT<br>(%) |
| 146+5        | PITCH TO ACQUIRE HORIZUN         | 32008,          | • 7                     | 703.7  | 52.                       |
| 146.5        | YAM 45 DEG                       | 32007.          | .7                      | 703•n  | 52.                       |
| 146.5        | ATT HOLD .5 DEG DB FGNCS         | 32007.          | . 4                     | 702+6  | 52.                       |
| 146.6        | CM/SM SEPARATION DELTA VEL=3 FPS | 17526.          | 40.8                    | 691.A  | 51.                       |

# TABLE 3-IV CM RCS PROPELLANT USAGE SUMMARY

| Loaded, lb.                                  |      | 210.0 |
|--|------|-------|
| Less   |      |       |
| Trapped, 1b.                                 | 32.4 |       |
| Temperature variation allowance, lb.         | 6.4  |       |
| Available for mission planning, lb.          |      | 231.2 |
| Nominal Usage                                |      |       |
| Separation and attitude hold prior to 0.05 g | 12.1 |       |
| Guidance commands for remainder of reentry   | 19.5 |       |
| Operational Reserve, 1b.                     |      | 199.6 |

TABLE 3-V Mission C Prime SPS Propellant Budget

| Item                         | Propellant (Lbs)   |
|------------------------------|--------------------|
| Loaded                       | 40785              |
| Trapped                      | -4 <sup>1</sup> 41 |
| Outage                       | - 18               |
| Unbalance Meter              | _100               |
| Available for $\Delta V$     | 40226              |
| Required for ΔV <sup>1</sup> | - <u>31253</u>     |
| Nominal Remaining            | 8973               |

Includes 14.4 lbs per start for start losses

 $I_{SP} = 314.25 \pm 1.593$ 

 $MR = 1.595 \pm 0.0067$ 

Vehicle Wt

CSM 22955.7

| Burn              | $\Delta V$ | Propellant Required |
|-------------------|------------|---------------------|
| TLMC <sup>2</sup> | 120.       | 780.0               |
| LOI               | 2991.      | 16074.7             |
| Circularization   | 138.5      | 648.5               |
| TEI               | 3531.7     | 13537.7             |
| TEMC              | 62         | 211.9               |
| 22 starts         |            | 31252.7             |

TABLE 3-VI

# CRYOGENIC CONSUMPTION ANALYSIS SUMMARY

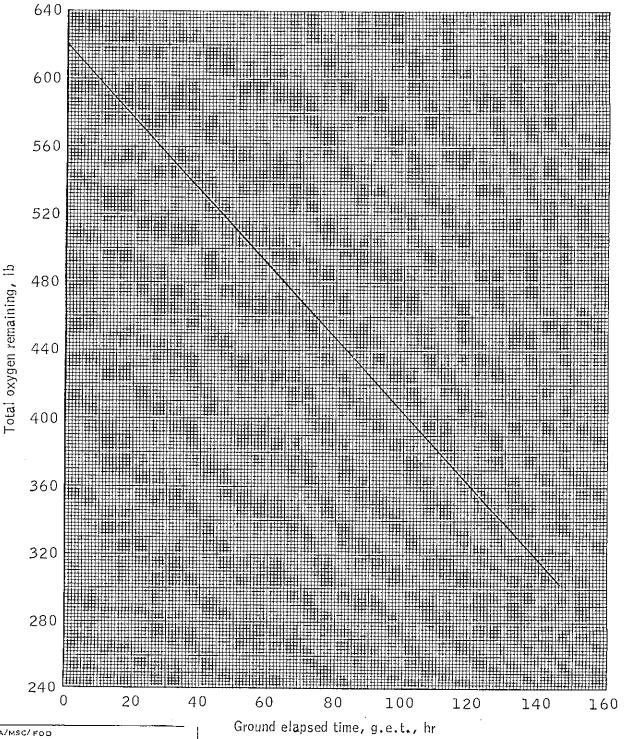
|   | 0 <sub>2</sub> (lbs)                     | H <sub>2</sub> (1bs)                |
|---|--|-------------------------------------|
| Loaded Residual & Instrumentation Error Available for mission Mission requirements Margin | 653.0<br>30.0<br>623.0<br>344.0<br>279.0 | 58.4<br>3.9<br>54.5<br>33.9<br>20.6 |

The results of the cryogenic consumption analysis are summarized in the following figures:

- 1. Figure -
- Nominal Mission  $0_2$  Profile.
- 2. Figure
- Nominal Mission H2 Profile.

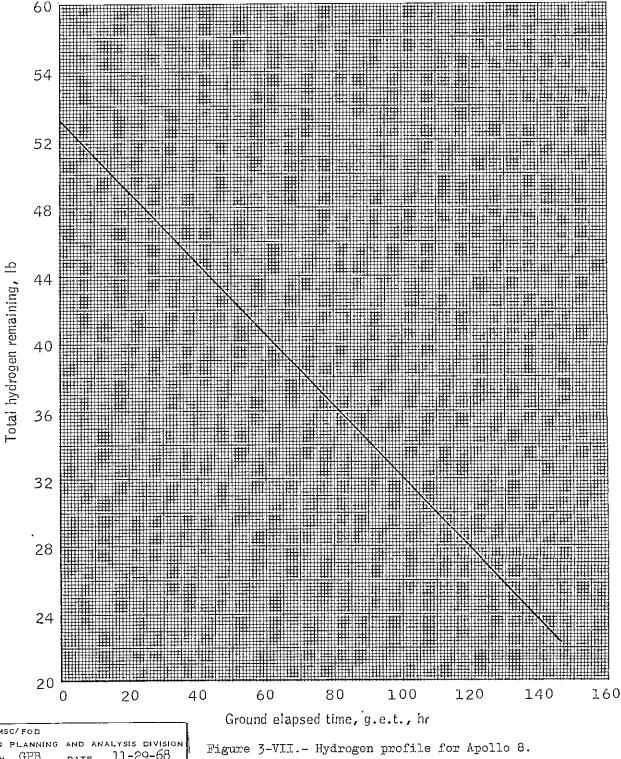
The following ground rules and assumptions were used for the contruction of the mission  $\rm H_2$  and  $\rm O_2$  profiles.

- 1. 10 fuel cell purges.
- 2. Cabin  $0_2$  leak rate of 0.2 lb/hr.
- 3. Metabolic O2 rate of 0.23 lb/hr for 3 crewmen.
- 4. Waste management 02 rate of 0.051 lb/hr.
- 5. Water tank  $0_2$  purge rate of 0.056 lb/hr.
- 6. The hydrogen consumption rate is .00257 lb/amp/hr.
- 7. The oxygen consumption rate is 7.936 times the hydrogen consumption rate.



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MISSION PLANNING AND ANALYSIS DIVISION
BRANCH GPB DATE 11-29-68
BY Scott PLOT NO. 386

Figure 3-VI.- Oxygen profile for Apollo 8.



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TABLE 3-VII

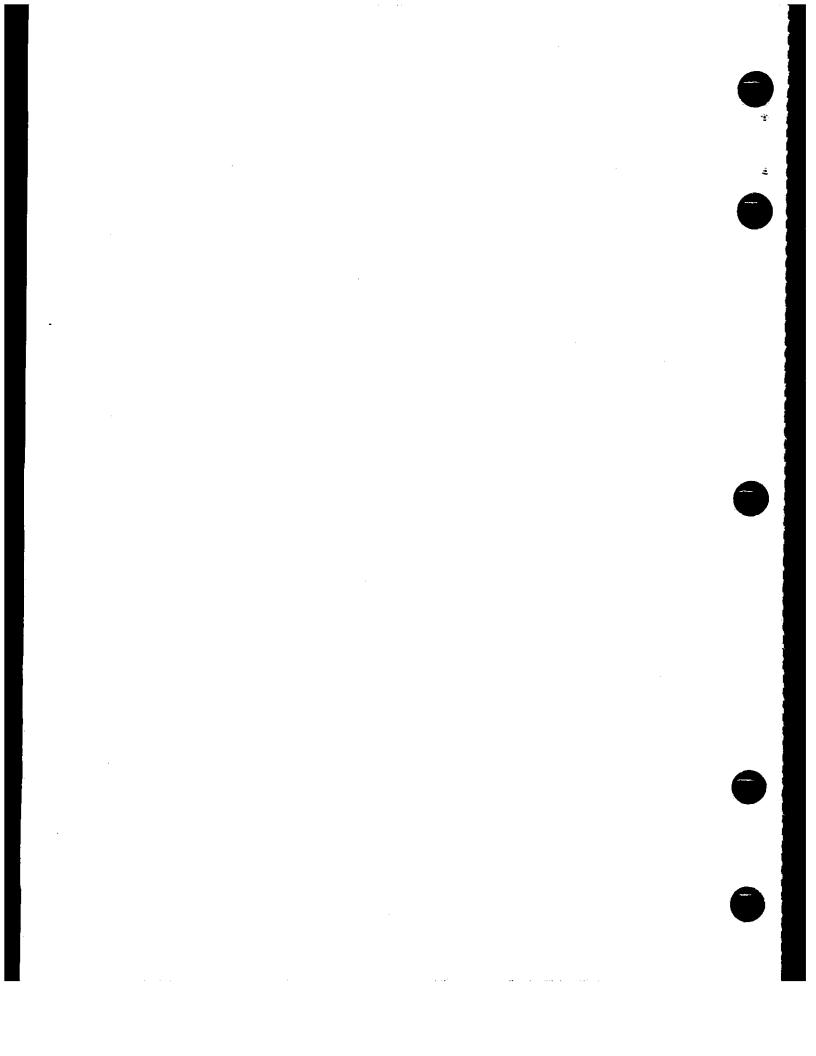
CREW CHECKLIST PROCEDURE/CONSUMABLES DATA SUMMARY
(AVERAGE ELECTRICAL POWER LOADS)

| CREW                                     | AVERAG   | E POWER  | BUS            | BATTERY     | BATTERY     | FUEL            | BUS   | CRYO CONS      | SUMPTION | H <sub>2</sub> O |
|--|----------|----------|----------------|-------------|-------------|-----------------|-------|----------------|----------|------------------|
| CHECKLIST<br>PROCEDURE                   | AC       | DC       | VOLTAGE        | CURRENT     | POWER       | CELL<br>CURRENT | POWER | н <sub>2</sub> | 02       | PRODUCTION       |
|  | WATTS    | WATTS    | VOLTS          | AMPS        | WATTS       | AMPS            | WATTS | LB/HR          | LB/HR    | LB/HR            |
| Contingency                              |          |          |                |             |             |                 | 1     |                |          |                  |
| Drift Flight 1. Normal                   | 676.6    | 1067.5   | 28.75          | _           | _ `         | 74.0            | 2130  | 0.189          | 1.50     | 1.69             |
| 2. Power Down                            | 676.6    | 905.9    | 28,90          |             | _           | 67.0            | 1940  | 0.174          | 1.38     | 1.55             |
|  | 0/0.0    | 900.9    | 20,90          | _           | _           | 07.0            | 1,40  | 0,1,4          | 1.50     | 1.33             |
| Boost thru Separa-<br>tion and Formation |          |          |                |             | 1           |                 | Į.    | ł              |          | 1                |
| 1  |          |          | ,              |             |             |                 | ļ     |                |          |                  |
| Flying 1. Lift-Off                       | 770.0    | 1085.0   | 29.30          | 19.0        | 556.0       | 58.0            | 2260  | 0.149          | 1.18     | 1.34             |
|  | 770.0    | 1000.0   | 29.30          | 19.0        | 3,00.0      | 0.00            | 2200  | 0.149          | 10       | . 1.54           |
| 2. 1st Stage Separa-                     | 779.1    | 1812.5   | 28.65          | 33.0        | 945.0       | 73.5            | 3060  | 0.189          | 1.50     | 1,69             |
| tion 3. Insertion (Earth                 | 779.1    | 1017.    | 20.03          | 22.0        | 945.0       | 75.5            | 3000  | 0.105          | 1.50     | 1.05             |
| Orbit)                                   | 734.9    | 1202.3   | 28,30          | _           | _           | 81.0            | 2290  | 0.208          | 1.65     | 1.86             |
|  | 734.9    | 1202.3   | 20.30          | _           | _           | 01.0            | 2290  | 0.200          | 1.03     | 1.00             |
| 4. TLI & Separation                      | 744.6    | 1179.5   | 28.30          | _           | _           | 81.0            | 2290  | 0.207          | 1.65     | 1.85             |
| Preparation                              | 744.0    | 111/9.5  | 20.30          | _           | 1 -         | 01.0            | 2290  | 0.207          | 1,00     | 1,05             |
| 5. Separation and                        | 761.1    | 1193.6   | 28.25          |             |             | 82.0            | 2320  | 0.210          | 1.67     | 1.88             |
| Formation Flying                         | 764.4    | 1133.0   | 20,23          | -           | ! -         | 02.0            | 2320  | 0,210          | 1.07     | 1,00             |
| Power Up                                 |          | Ì        |                |             |             |                 | ļ     |                |          |                  |
| 1. Stabilization and                     |          | 7700 0   | 28.35          |             |             | 80.0            | 2270  | 0.206          | 1.64     | 1.84             |
| Control                                  | 767.0    | 1128.0   |                | -           | _           | 77.5            | 2210  | 0.200          | 1.59     | 1.77             |
| 2. G&N Optics                            | 681.8    | 1156.6   | 28.45<br>28.25 | _           | _           | 82.5            | 2330  | 0.133          | 1.68     | 1.90             |
| 3. Stabilization and Control, and G&N    | 112.2    | 1217.1   | 28,23          | _           | _           | 02.5            | 2330  | 0.213          | 1,00     | 1.50             |
| Optics                                   | !        | 1        |                |             | l           |                 |       |                |          | 1                |
| G&N/SPS Orbit Change                     |          | 1        |                |             | 1           | }               |       |                |          |                  |
| 1. Initial Condi-                        |          |          | 00.00          |             | 1           | 07.0            | 2290  | 0.208          | 1.65     | 1.86             |
| tions                                    | 774.8    | 1156.8   | 28.30          | -           | -           | 81.0            | 2290  | 0.200          | T.02     | 1.00             |
| 2. Ignition Prepara-                     |          | ·        |                |             | 1           | 7, 0            | 20.00 | 0.700          | 7 50     | 1.71             |
| tion                                     |          | 1897.5   | 28.60          |             |             | 74.0            | 3080  | 0.192          | 1.52     | 2.00             |
| 3. Ignition                              | 868.5    | 2458     | 28.05          | 45.0        | 1260        | 86.5            | 3690  | 0.224          | 1.78     | 1.76             |
| Battery Charging                         | 724.6    | 1116.5   | 28.5           |             | <u> </u>    | 77.0            | 2190  | 0.197          | 1.57     | 1.70             |
| G&N SM RCS Orbit                         | 1        | 1        |                |             |             |                 |       |                |          |                  |
| Change Thrusting                         | 1        | İ        | l              |             | 1           |                 |       |                |          | 1                |
| (P41)                                    | ,        |          |                | 1           |             | 22.6            | 0000  | 0.010          | 1.66     | 1.87             |
| 1. Initial Condi-                        | 774.8    | 1170.2   | 28.3           | -           | <u> </u>    | 82.0            | 2320  | 0.210          | 7.00     | 1.07             |
| tions                                    |          | İ        |                | ŀ           |             |                 |       | 1              |          |                  |
| }  |          | !        |                | [           |             | 1               | ]     | 1              |          |                  |
|  | <u> </u> | <u> </u> | l              | <del></del> | <del></del> | L               | L     | <del></del>    | <u></u>  | <del></del>      |

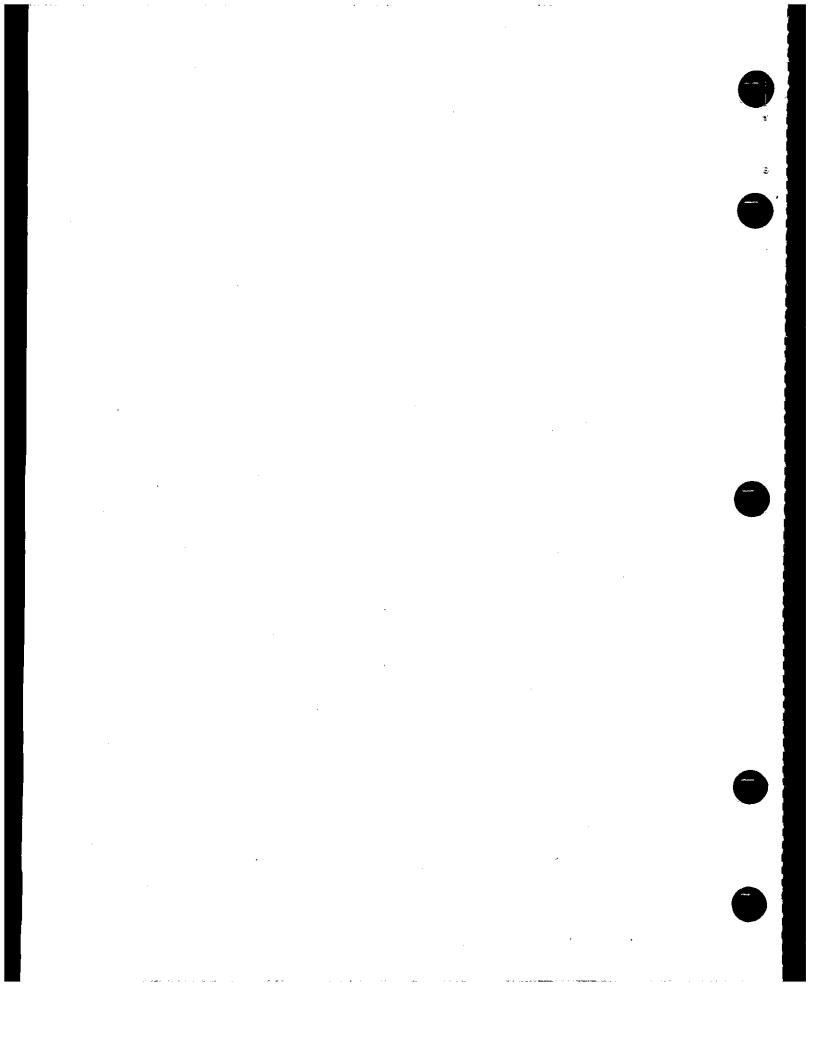
3-45

# CREW CHECKLIST PROCEDURE/CONSUMABLES DATA SUMMARY (AVERAGE ELECTRICAL POWER LOADS)

| CREW  | AVERAG                           | AVERAGE POWER   |                              |                              |                                    |                        |                                  | BATTERY FUEL B |                        | CRYO CONS  | UMPTION | н <sub>2</sub> о |
|---|----------------------------------|-----------------|------------------------------|------------------------------|------------------------------------|------------------------|----------------------------------|----------------|------------------------|------------|---------|------------------|
| CHECKLIST<br>PROCEDURE  | AC                               | DC              | VOLTAGE:                     | CURRENT                      | POWER                              | CELL<br>CURRENT        | POWER                            | н2             | 02                     | PRODUCTION |         |                  |
| F ROCEDORE.   | WATTS                            | WATTS           | VOLTS                        | AMPS                         | WATTS                              | AMPS                   | WATTS                            | LB/HR          | LB/HR                  | LB/HR      |         |                  |
| 2. Ignition   | 774,8                            | 1602.2          | 27,6                         | _                            | _                                  | 97.0                   | 2680                             | 0.250          | 1.99                   | 2.24       |         |                  |
| Entry to Landing 1. Preparation 2. CM RCS Htrs 3. CM SM Separation 4. Entry | 684.4<br>684.4<br>501.8<br>492.3 | 1659.2<br>760.6 | 29.6<br>29.2<br>28.5<br>28.6 | 23.0<br>34.0<br>55.0<br>56.5 | 680.0<br>993.0<br>1565.0<br>1605.0 | 52.0<br>62.0<br>-<br>- | 2220<br>2800<br>1565.0<br>1605.0 |                | 1.06<br>1.26<br>-<br>- | 1.20       |         |                  |
| Post Landing  | _                                | 86.0            | 28.0                         | 3.07                         | 86.0                               | -                      | 86,0                             | -              | _                      | _          |         |                  |
|   |                                  |                 |                              |                              |                                    |                        |                                  |                |                        |            |         |                  |
|   |                                  |                 |                              |                              |                                    |                        |                                  |                |                        |            |         |                  |



SECTION IV - DETAILED TEST OBJECTIVES



#### SECTION 4

#### TEST OBJECTIVE ACTIVITIES

This section contains the activity summaries which reflect the test objectives for Mission C' as described in "Mission Requirements AS 503/CSM 103 C' Type Mission (Lunar Orbit)" dated November 16, 1968. These activity summaries are presented in the approximate sequence in which they are planned to occur during the mission. In the case of activities which are repeated in the mission plan, they are described only once in this summary. Those test objectives which do not relate to specific mission activities are grouped at the end of this section as "Miscellaneous Tests" and "Telecommunications". Test objective requirements which are not scheduled in this flight plan are identified as being not implemented, "N.I."

Each activity summary provides the following information:

- A. TEST OBJECTIVES. This is the listing of the Functional Test Objectives (complete or partial) which relate to the particular activity;
- B. TEST REQUIREMENTS. Here the special test prerequisites are presented in addition to brief statements of the requirements for performing the activity;
- C. TEST PROCEDURES/CHECKLISTS. These are the procedural references for the performance of the activity as far as the test objectives are concerned; and
- D. DATA REQUIREMENTS. This part of the summary identifies the gross data which are needed for evaluation of test results in terms of flight crew and ground support requirements.

A cross reference for relating Detailed and Functional Test Objectives with the activity summaries is provided as the initial part of this section.

The following ground rules are to be used in implementing data requirements:

- A. The collection of highly desirable (HD) data should not constrain the timeline or the crew procedures.
- B. CSM data storage equipment (DSE) HBR recording is needed only when MSFN coverage is not available and when mandatory data are required.
- C. Data collected by the crew which are required only for postflight analysis, need not be voiced to MSFN in real time.

| DTO/FTO<br>NUMBER  | TEST OBJECTIVE   | MISSION ACTIVITY   | SECTION PAGE NO.                      |
|--|--|--|---------------------------------------|
| S1.27<br>S1.27-1<br>S1.27-2  | GNCS Boost Monitor/Saturn V Boost Monitor - GNCS Performance Boost Monitor - Display Adequacy  | Launch<br>Launch   | -4-8<br>4-8                           |
| \$1.30<br>\$1.30-1<br>\$1.30-2<br>\$1.30-3                         | IMU Performance GNCS Accelerometer Biases During Coasting Flight GNCS/IRIG Drift Rates During Coasting Flight Overall GNCS Errors During Thrusting Maneuvers   | PIPA Bias Check<br>IMU Realignment<br>Lunar Orbit Insertion  | 4-18<br>4-15<br>4-8,27                |
| P1.31<br>P1.31-1<br>P1.31-2  | GNCS Entry Lunar Return GNCS Performance During Entry - Lunar Return EMS Capability to Monitor Entry - Lunar Return  | Entry<br>Entry   | 4-12,35<br>4-12,35                    |
| \$1.32<br>\$1.32-1<br>\$1.32-2<br>\$1.32-3<br>\$1.32-4<br>\$1.32-5 | Midcourse Navigation/Star Earth - Landmark Star/Earth Landmark Navigation Sighting Accuracy Verify and Update Landmark Lighting Constraints OSS Adequacy for Navigation Sightings in Deep Space Crew Capability to Identify Landmarks and Coordinate Optics/Maneuvers RCS Propellant Use and Time to Accomplish Onboard Navigation | Star/Earth Landmark Navigation<br>Star/Earth Landmark Navigation<br>Star/Earth Landmark Navigation<br>Star/Earth Landmark Navigation<br>Star/Earth Landmark Navigation | 4-11,20<br>4-11,20<br>4-11,20<br>4-20 |
| P1.33<br>P1.33-1<br>P1.33-2<br>P1.33-3<br>P1.33-4                  | Midcourse Navigation/Star-Lunar Horizon Star/Lunar Horizon Navigation Sighting Accuracy OSS Adequacy for Navigation Sightings in Deep Space Crew Capability to Coordinate Optics/Maneuvers RCS Propellant Use and Time to Accomplish Onboard Navigation  | Star/Lunar Horizon Navigation<br>Star/Lunar Horizon Navigation<br>Star/Lunar Horizon Navigation<br>Star/Lunar Horizon Navigation                                       | 4-24<br>4-24<br>4-24<br>4-24          |
|  |  |  |                                       |

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| DTO/FTO<br>NUMBER                                 | TEST OBJECTIVE   | MISSION ACTIVITY  | SECTION<br>PAGE NO.                   |
|---|--|---|---------------------------------------|
| P1.34<br>P1.34-1<br>P1.34-2<br>P1.34-3<br>P1.34-4 | Midcourse Navigation/Star-Earth Horizon Star/Earth Horizon Navigation Sighting Accuracy Verify and Update Horizon Lighting Constraints OSS Adequacy for Navigation Sightings in Deep Space Crew Ability to Identify Horizon Locator and Coordinate Optics/Maneuvers RCS Propellant Use and Time to Accomplish Onboard Navigation | Star/Earth Horizon Navigation<br>Star/Earth Horizon Navigation<br>Star/Earth Horizon Navigation<br>Star/Earth Horizon Navigation<br>Star/Earth Horizon Navigation | 4-16<br>4-16<br>4-16<br>4-16<br>4-16  |
| S1.35<br>S1.35-1<br>S1.35-2<br>S1.35-3            | IMU Orientation Determination/Visibility IMU Realignment in Daylight Obtain Data - Star Visibility During TL and TE Coast Degradation of Navigation/IMU Align by Vented/Ejected Particles  | IMU Realignment<br>Star Visibility<br>Star Visibility   | 4-31<br>4-15<br>4-26<br>4-26          |
| S3.21<br>S3.21-1<br>S3.21-2<br>S3.21-3<br>S3.21-4 | SPS Evaluation SPS I <sub>SP</sub> - Adequacy of Conversion - Ground to Vacuum Results SPS Performance for LOI and TEI Burns SPS PUGS in Auxiliary Mode - Relative Accuracy Aux/Pri Thermal Effects - Long SPS Burn - Heat Protection System   | LOI and TEI LOI and TEI TEI LOI and TEI   | 4-27,33<br>4-27,33<br>4-33<br>4-27,33 |
| S4.5<br>S4.5-1<br>S4.5-2                          | ECS Lunar Return Entry ECS Performance During Manned Lunar Return Entry Compare ECS Data with Developed Model and Unmanned Results   | Entry<br>Entry  | 4-35<br>4-35                          |
| S6.10<br>S6.10-1                                  | CSM Omni Antennas Lunar Distance<br>S-Band Performance with Omni Antennas at Lunar Distance  | Telecommunications  | 4 <b>–</b> 38                         |
|   |  |   |                                       |

| DTO/FTO<br>NUMBER                              | TEST OBJECTIVE   | MISSION ACTIVITY  | SECTION<br>PAGE NO.                  |
|--|--|---|--------------------------------------|
| P6.11<br>P6.11-1<br>P6.11-2<br>P6.11-3         | CSM/MSFN Communications Lunar Distance<br>S-Band Performance with High Gain Antenna - TL Coast<br>S-Band Performance with High Gain Antenna - Lunar Distance<br>CSM HGA Oper. in Potential S/C Reflectivity Region | Telecommunications<br>Telecommunications<br>Not Implemented                                   | 4–38<br>4–38                         |
| \$7.30<br>\$7.30-1<br>\$7.30-2                 | Heat Shield Lunar Return<br>Block II Thermal Protection System During Manned Lunar Return<br>TPS Surface Recession and Char Data Comparison  | Entry<br>Entry  | 4-35<br>4-35                         |
| P7.31<br>P7.31-1<br>P7.31-2                    | Spacecraft Environment Thermal Control<br>Evaluate Thermal Control System During TL and TE Coast<br>Thermal Control System During Lunar Orbit  | Miscellaneous Tests<br>Miscellaneous Tests  | 4-20,36<br>4-20,36                   |
| P7.32<br>P7.32-1<br>P7.32-2<br>P7.32-3         | Spacecraft Dynamic Environment<br>CSM Loads/Vibrations - Launch, TLI and Separation<br>SLA Dynamic Response - Launch, TLI and Separation<br>S-Band HGA Response During Deployment and SPS Burns                    | Launch', TLI, CSM/S-IVB Sep.<br>Launch, TLI, CSM/S-IVB Sep.<br>CSM/S-IVB Sep., Midcourse, LOI | 4-8,11,12<br>4-8,11,12<br>4-19,12,27 |
| P7.33<br>P7.33-1                               | SLA Panel Jettison<br>SLA Panel Jettison Demonstration   | CSM/SIVB Separation   | 4-14<br>4-14                         |
| S20.104<br>S20.104-1<br>S20.104-2<br>S20.104-3 | Transposition<br>Separation and Transposition Maneuver<br>Separation and Transposition Procedures and Timeline Adequacy<br>S-Band Performance During Transposition   | CSM/S-IVB Sep., Transposition<br>CSM/S-IVB Sep., Transposition<br>Telecommunications          | 4-12,13,14<br>4-12,13<br>4-38        |
|  |  |   |                                      |
|  |  |   |                                      |

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| DTO/FTO<br>NUMBER  | TEST OBJECTIVE   | MISSION ACTIVITY   | SECTION PAGE NO.                     |
|--|--|--|--------------------------------------|
| P20.105<br>P20.105-1<br>P20.105-2  | LOI Maneuver<br>Crew/Spacecraft/MSFN Preparation and Execution of LOI<br>Maneuver<br>Procedures and Timeline Adequacy for LOI Maneuver | Lunar Orbit Insertion<br>Lunar Orbit Insertion   | 427<br>427                           |
| P20.106<br>P20.106-1<br>P20.106-2  | TEI Maneuver<br>Crew/Spacecraft/MSFN Preparation and Execution of TEI<br>Maneuver<br>Procedures and Timeline Adequacy for TEI Maneuver | Transearth Insertion Transearth Insertion  | 4-33<br>4-33                         |
| P20.107<br>P20.107-1<br>P20.107-2  |  | Miscellaneous Tests<br>Miscellaneous Tests   | 4–36<br>4–36                         |
| \$20.108<br>\$20.108-1<br>\$20.108-2<br>\$20.108-3<br>\$20.108-4<br>\$20.108-5 | Water and Oxygen Requirements Data LiOH Cartridge Requirements Data SPS, SM/RCS and CM/RCS Propellant Requirements Data                | Miscellaneous Tests Miscellaneous Tests Miscellaneous Tests Miscellaneous Tests Miscellaneous Tests          | 4-36<br>4-36<br>4-36<br>4-36<br>4-36 |
| P20.109<br>P20.109-1<br>P20.109-2<br>P20.109-3<br>P20.109-4                    | Communication Procedures Adequacy for PTC Mode   | Passive Thermal Control Modes Passive Thermal Control Modes Telecommunications Passive Thermal Control Modes | 4-22<br>4-22<br>4-22,38<br>4-22      |
| P20.110<br>P20.110-1   | Ground Support Lunar Distance<br>Ground Operation Support for Lunar Mission Without LM   | Miscellaneous Tests  | 4-36                                 |

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| DTO/FTO  | TEST OBJECTIVE  |   | SECTION  |
|--|---|---|--|
| NUMBER   | · · · · · · · · · · · · · · · · · · ·   | MISSION ACTIVITY  | PAGE NO.   |
| P20.111<br>P20.111-1<br>P20.111-2<br>P20.111-3<br>P20.111-4<br>P20.111-5<br>P20.111-6<br>P20.111-7 | Lunar Landmark Tracking Error Uncertainties in Lunar Landing Site Location Obtain Data to Calibrate MSFN at Lunar Distance Determine Minimum Sun Angle to Clearly Identify Landmarks Lunar Landmark Tracking in Earthshine Adequacy of CSS and OSS for Obtaining Landmark Sightings Crew Ability to Coordinate Sightings and Vehicle Maneuvers RCS Propellant and Time Required for Landmark Sighting | Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking Lunar Landmark Tracking | 4-29<br>4-29<br>4-29<br>4-29<br>4-29<br>4-29<br>4-29 |
| P20.112<br>P20.112-1<br>P20.112-2<br>P20.112-3<br>P20.112-4<br>P20.112-5                           | TLI Burn Crew/Ground Capability for TLI at First Opportunity TLI Preparation and Execution Procedure Demonstration TLI Procedures and Timeline Adequacy CSM Cabin Vibration Environment during TLI Burn Crew Monitoring of GNCS and LV Displays - TLI Burn  | Pre-TLI and TLI Pre-TLI and TLI Pre-TLI and TLI Translunar Injection Translunar Injection   | 4-10<br>4-10,11<br>4-10,11<br>4-11<br>4-11           |
| P20.114<br>P20.114-1<br>P20.114-2<br>P20.114-3   | Midcourse Correction Capability Procedures and Timeline Adequacy for MCC'S GNCS, SPS and RCS Performance on MCC'S Ground Capability to Update State Vector and Target for MCC   | Midcourse Corrections<br>Midcourse Corrections<br>Midcourse Corrections   | 4-19<br>4-19<br>4-19                                 |
| \$20.115<br>\$20.115-1<br>\$20.115-2<br>\$20.115-3<br>\$20.115-4                                   | Lunar Mission Photography from the CSM Overlapping Photos from Terminator to Terminator-Lunar Orbit Photos of Earth and Lunar Landmarks Photos of Earth and Lunar Horizons  Photos of General and Scientific Interest   | Photography Photo, S/E Landmark Nav. Photo, S/E Landmark Nav., S/L Landmark Nav. Photography  | 4-31<br>4-20<br>4-16,24,31<br>4-31                   |
|  |   |   |  |

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| DTO/FTO<br>NUMBER                    | TEST OBJECTIVE   | MISSION ACTIVITY              | SECTION<br>PAGE NO. |
|--------------------------------------|--|-------------------------------|---------------------|
| \$20.116<br>\$20.116-1<br>\$20.116-2 | Exhaust Effects/CSM Windows<br>Changes in Visual Acuity Through Windows<br>Changes in Total Transmittance of Windows | Launch Transposition<br>Entry | 4-8,13<br>4-35      |
|                                      |  | -                             |                     |
|                                      |  |                               |                     |
|                                      |  |                               |                     |
|                                      |  |                               |                     |
|                                      |  |                               |                     |
|                                      |  |                               |                     |
|                                      |  |                               |                     |
|                                      |  |                               |                     |

#### LAUNCH

#### A. TEST OBJECTIVES

- S1.27-1 Boost Monitor GNCS Performance
- S1.27-2 Boost Monitor Display Adequacy
- S1.30-3 Overall GNCS Errors During Thrusting Maneuvers
- P7.32-1 CSM Loads/Vibrations S-V Boost
- P7.32-2 SLA Dynamic Response S-V Boost
- S20.116-1 Changes in Visual Acuity Through Windows

### B. TEST REQUIREMENTS

- 1. CSM insertion into earth orbit by a Saturn V vehicle [1.27, 1.30, 7.32 & 20.116]
- 2. FQTR operation throughout Saturn V boost [7.32]
- 3. Crew observations of changes in visual acuity through the windows as the result of TJM firing & S-II retro firing [20.116]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.3.1 "Boost and Insertion"
- 2. FCAC L-1, L-2, & L-3 "Boost-Insertion"

#### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. FDAI or DSKY display inadequacies [1.27] (M)
  - b. Apparent GNCS trajectory errors [1.27] (M)
  - c. Unexpected structural loads or vibrations [7.32] (M)
  - d. Log changes in visual acuity through windows ("Window Visibility" log) [20.116] (M)

#### 2. Ground Support

- a. CSM TM HBR [1.27, 7.32] (M)
- b. Continuous tracking [1.27] (M)
- c. BET [7.32] (M)
- d. Dynamic pressure & angle of attack during S-IC operation [7.32] (M)
- e. Wind data from 0 to 60,000 ft at launch time [7.32] (M)

- f. Saturn V thrust variations vs. time-MSFC [7.32] (M)
- g. Saturn V accel & IU gyro data MSFC [7.32] (M)

#### PRE-TLI

#### A. TEST OBJECTIVES

- P20.112-1 Crew/Ground Capability for TLI at First Injection Opportunity
- P20.112-2 TLT Preparation and Execution Procedure Demonstration
- P20.112-3 TLI Procedures and Timeline Adequacy

#### B. TEST REQUIREMENTS

- Following earth orbit insertion, flight crew accomplishment of all pre-TLI activities required for a Pacific injection on the second pass
- 2. Ground operational support personnel evaluation of all spacecraft systems and making of the go/no-go decision for the TLI burn

#### C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.3.2 "Post Orbital Insertion Check"
- 2. AOH paragraph 4.4.1 "Translunar Injection"
- 3. FCAC L-4, L-5, L-1, & L-2 "Post Insertion"
- 4. FCAC L-6 & L-7 "System Verification & Monitoring"
- 5. FCAC L-8 & L-9 "TLI Preparation" to GET 02:50:38

#### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Procedural and/or timeline difficulties or inadequacies (M)
  - Comments regarding feasibility of first Atlantic injection opportunity during the second revolution (M)

#### 2. Ground Support

a. Flight Director reports of timeline and/or procedural difficulties (M)

#### TRANSLUNAR INJECTION

### A. TEST OBJECTIVES

- P7.32-1 CSM Loads/Vibrations TLI
- P7.32-2 SLA Dynamic Response TLI
- P20.112-2 TLI Preparation and Execution Procedure Demo.
- P20.112-3 TLI Procedures and Timeline Adequacy
- P20.112-4 CSM Cabin Vibration Environment During TLI Burn
- . P20.112-5 Crew Monitoring of GNCS & LV Displays During TLI

#### B. TEST REQUIREMENTS

- Ground operational support and flight crew capability to execute the TLI burn [20.112]
- 2. FQTR operation throughout the S-IV burn [7.32]
- C. TEST PROCEDURES/CHECKLISTS
  - 1. AOH paragraph 4.4.1 "Translunar Injection"
  - 2. FCAC L-9 & L-10 "TLI Preparation"
- D. DATA REQUIREMENTS
  - 1. Flight Crew Reports/Logs
    - a. Procedural and/or timeline difficulties or inadequacies [20.112] (M)
    - b. FDAI, DSKY & LV Tank Pressure display inadequacies [20.112] (M)
    - c. Unexpected induced resonances in cabin (Visual, audible and tactile) [20.112] (M)
    - d. Comments on adequacy of TLI monitoring [20.112] (M)
  - 2. Ground Support
    - a. CSM TM HBR [7.32] (M)
    - b. Flight Director reports of procedural and/or timeline difficulties or inadequacies [20.112] (M)

#### CSM/S-IVB SEPARATION

#### A. TEST OBJECTIVES

- P7.32-1 CSM Loads/Vibrations CSM/S-IVB Separation
  P7.32-2 SLA Dynamic Response CSM/S-IVB Separation
  P7.32-3 S-Band High Gain Antenna Dynamic Response During Deployment
  S20.104-1 Separation and Transposition Maneuver
- S20.104-1 Separation and Transposition Procedures & Timeline Adequacy

#### B. TEST REQUIREMENTS

- 1. CSM/S-IVB separation, SLA panel jettison and S-band high gain antenna deployment [20.104]
- FQTR operation during the period of the CSM/S-IVB separation, SLA panel jettison and S-band high gain antenna deployment [7.32]

#### C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.5.1.1, "CSM/SLA Separation Through Capture Latch" through step 5
- 2. FCAC Separation TBD

#### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Procedural and/or timeline difficulties or inadequacies [20.104] (M)

#### 2. Ground Support

- a. CSM TM HBR [7.32] (M)
- b. Flight Director reports of procedural and/or timeline difficulties or inadequacies [20.104] (M)

#### TRANSPOSITION

# A. TEST OBJECTIVES

S20.104-1 Separation and Transposition Maneuver

S20.104-2 Transposition Procedures and Timeline Adequacy

S20.116-1 Changes in Visual Acuity Through Windows

#### B. TEST REQUIREMENTS

- After separation, a (+X) translation from the S-IVB for three seconds, a coast for one minute to approximately 70 ft., a (-X) translation for 1 1/2 seconds, and then a pitch up at 4°/sec until the spacecraft (+X) axis points at the S-IVB [20.104]
- 2. Determination if there are any changes in visual acuity through the windows as the result of SM RCS use [20.116]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.5.1.1, "CSM/SLA Separation Through Capture Latch" step 6
- 2. FCAC Transposition TBD

# D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Procedural and/or timeline difficulties or inadequacies
     [20.104] (M)
  - b. Inadequacies in communications with ground operational support [20.104] (M)
  - c. Log changes in visual acuity through the windows from SM RCS use ("Window Visibility" log) [20.116] (M)

#### 2. Ground Support

- a. CSM TM HBR [20.104] (M)
- b. USB tracking data processor output recording [20.104] (M)
- c. USB TM bit stream recording [20.104] (M)
- d. MSFN tape records of S-band received signal strength [20.104] (M)
- e. MSFN tape recordings of CSM to MSFN and MSFN to CSM voice [20.104] (M)
- f. Flight Director reports of procedural and/or timeline difficulties or inadequacies [20.104] (M)
- g. BET [20.104] (M)

#### FORMATION FLYING

#### A. TEST OBJECTIVES

P7.33-1 SLA Panel Jettison Demonstration S20.104-1 Separation and Transposition Maneuver

### B. TEST REQUIREMENTS

- 1. Formation flying with the S-IVB to acquire the following photographs:
  - a. Sequence camera photographs of the S-IVB following transposition [20.104] (HD)
  - b. Photographs of the SLA aft portion and LTA-B showing that the panels jettisoned and of any anomaly observed [7.33] (M)

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.5.1.2 "Formation Flight With S-IVB (General)"
- 2. Photo checklist TBD

### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Observed anomalies in the jettison of the SLA panels or launch vehicle instability [7.33] (M)
  - b. Disposition of any observed SLA panels [7.33] (M)
  - c. Sequence photographs of the S-IVB following transposition [20.104] (HD)
  - d. Photographs of the SLA aft portion and the LTA-B showing that the panels jettisoned and of any anomalies observed [7.33] (M)

#### 2. Ground Support

a. None

#### IMU REALIGNMENT

#### A. TEST OBJECTIVES

S1.30-2 GNCS IRIG Drift Rates During Coasting Flight S1.35-1 IMU Realignment in Daylight

# B. TEST REQUIREMENTS

- 1. At least two sets of back-to-back IMU realignments (at least one hour apart without an intervening  $\Delta V$  maneuver) to determine IRIG drift rates [1.30]
- One IMU realignment in daylight when at an altitude of greater than 2000 NM [1.35]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.11.1 "IMU Orientation Determination (P51)" or
- 2. AOH paragraph 4.11.2 "IMU Realign (P52)"
- 3. FCAC "P51 IMU Orientation" or
- 4. FCAC "P52 IMU Realign"

# D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs None
- 2. Ground Support CSM TM [1.30] (M)

# STAR/EARTH HORIZON NAVIGATION

#### A. TEST OBJECTIVES

- Pl.34-1 Star/Earth Horizon Navigation Sighting Accuracy
- P1.34-2 Verify and Update Horizon Lighting Constraints
- Pl.34-3 OSS Adequacy for Navigation Sightings in Deep Space
- P1.34-4 Crew Ability to Identify Horizon Locator and Coordinate Optics/Maneuvers
- P1.34-5 RCS Propellant Use and Time to Accomplish Onboard Navigation
- S20.115-3 Photographs of Earth and Lunar Horizons

#### B. TEST REQUIREMENTS

- Use of the trunnion calibration option of P23 preceding a set of sightings if more than about 30 minutes has elapsed since the previous P23 trunnion calibration [1.34]
- 2. Translunar Near Earth
  - a. Five sets of star/earth horizon sightings at more than  $15,000~\mathrm{NM}$  and less than  $50,000~\mathrm{NM}$  from the center of the earth [1.34]
  - b. At least 10 sequence photographs through the special sextant camera adapter while duplicating star/horizon navigation sightings when between 10,000 and 30,000 NM from the earth on TL phase. It is desirable that these photographs be taken at varying distances [20.115] Not Implemented
  - c. Update of the onboard state vector utilizing the navigation sighting data following each set of sightings [1.34]

#### 3. Translunar - Midcourse

- a. Eighteen sets of star/earth horizon sightings at more than 50,000 NM from both the earth and the moon [1.34]
- b. Update of the onboard state vector utilizing the navigation sighting data following each set of sightings [1.34]

#### 4. Transearth

- a. Star/earth horizon sightings under the following conditions [1.34]
  - (1) Seventeen sets at more than 50,000 NM from the earth and moon
  - (2) Three sets at less than 50,000 NM from the center of the earth
- b. Update of the onboard state vector utilizing the navigation sighting data following each set of sightings [1.34]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.12.3 "Cislumar Midcourse Navigation (P23) including "Trunnion Calibration" option
- 2. FCAC G-20A "P23 Cislunar Midcourse Navigation Measurement"
- 3. Photo checklist TBD

# D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Difficulties and/or inadequacies noted in handling the optics and the spacecraft [1.34] (M)
  - b. Log navigation data on Flight Plan timeline [1.34] (M)
  - c. Photo log TBD [20.115] (M)
- 2. Ground Support
  - a. CSM TM HBR [1.34] (M)
  - b. ВЕТ [1.34] (M)

#### PIPA BIAS CHECK

#### A. TEST OBJECTIVES

S1.30-1 GNCS Accelerometer Biases During Coasting Flight

#### B. TEST REQUIREMENTS

- 1. MSFN collection of PIPA bias data at least five times during the mission using uninterrupted TM for at least five minutes as follows:
  - a. Prior to and following an SPS burn of at least 40 seconds
  - b. As close to entry as possible
  - c. Any two other periods in the mission
- 2. Onboard test performed only if communications are lost

#### C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.10.1.13 "Measurement and Loading of PIPA Bias"
- 2. FCAC G-51 "Measure & Load PIPA Bias"

#### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Log PIPA bias data on Flight Plan timeline if PIPA bias tests are performed onboard
- 2. Ground Support
  - a. CSM TM (M)

#### MIDCOURSE CORRECTIONS

#### A. TEST OBJECTIVES

P7.32-3 S-Band High Gain Antenna Dynamic Response During SPS burns P20.114-1 Procedures and Timeline Adequacy for Midcourse Corrections P20.114-2 GNCS, SPS & RCS Performance on Midcourse Corrections P20.114-3 Ground Capability to Update State Vector and Target for MCC

#### B. TEST REQUIREMENTS

- 1. Ground update of the CSM state vector and of the MCC target [20.114]
- 2. MCC maneuver performance [20.114]
- 3. FQTR operation during SPS ignition, cutoff and for at least five seconds during the burn [7.32]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.10.1.5 "CSM-CMC Update P27"
- 2. AOH paragraph 4.14.2 "G&N/SPS Orbit Change Thrusting (P40)" or
- 3. AOH paragraph 4.14.3 "G&N SM RCS Orbit Change Thrusting (P41)"
- 4. FCAC G-21 "P27 CMC Update
- 5. FCAC G-30 "P40 SPS Thrust" or
- 6. FCAC G-37 "P41 RCS Thrust"

#### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Procedural and/or timeline difficulties or inadequacies
     [20.114] (M)

#### 2. Ground Support

- a. CSM TM HBR [20.114] (M)
- b. ВЕТ [20.114] (M)
- Flight Director reports of procedural and/or timeline difficulties or inadequacies [20.114] (M)

## STAR/EARTH LANDMARK NAVIGATION

#### A. TEST OBJECTIVES

| S1.32-1 | Star/Earth Landmark Navigation Sighting Accuracy     |
|---------|--|
| S1.32-2 | Verify and Update Landmark Sighting Constraints      |
| S1.32-3 | OSS Adequacy for Navigation Sightings in Deep Space  |
| S1.32-4 | Crew Capability to Identify Landmarks and Coordinate |
|         | Optics/Maneuvers                                     |
| 01 DO F |  |

S1.32-5 RCS Propellant Use and Time to Accomplish Onboard Navigation S20.115-2 Photographs of Earth and Lunar Landmarks

#### B. TEST REQUIREMENTS

- 1. Use of the trunion calibration option of P23 preceding these sets of sightings
- 2. Star/earth landmark sightings under the following conditions [1.32]:
  - a. Three sets after TLI while the spacecraft is less than 50,000 NM from the surface of the earth (TL or TE). These sightings may be made on the same landmark but three different stars will be used
  - b. One set at a sun elevation angle of less than ten degrees. One of the above sightings can be used to satisfy this requirement
    - Note Performing sightings on one landmark and one star, then making from three to five "marks" constitutes one set of sightings
- 3. Approximately ten sequence photographs through the special sextant camera adapter immediately after performing each group of star/earth landmark sightings. This photography must not jeopardize any nav sightings [20.115] Not Implemented
- 4. Identification of the landmark closest to sunrise or sunset that is considered acceptable for landmark tracking [1.32]

#### C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.12.3 "Cislunar Midcourse Navigation (P23)" including "trunion calibration" option
- 2. FCAC G-20A "P23 Cislunar Midcourse Nav Measurement"
- 3. Photo checklist TBD

#### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Difficulties and/or inadequacies noted in handling the optics and the spacecraft [1.32] (M)

- b. Log navigation data on Flight Plan timeline [1.32] (M)
- c. Photo log TBD [20.115] (HD)
- 2. Ground Support
  - a. CSM TM HBR [1.32] (M)
  - b. BET [1.32] (M)

# PASSIVE THERMAL CONTROL MODES

### A. TEST OBJECTIVES

| P109-1 | PTC Procedures & RCS Use - Roll With Att. Hold  |
|--------|---|
| P109-2 | PTC Procedures & RCS Use - Roll W/O Att. Hold   |
| P109-3 | Communications Procedures Adequacy for PTC Mode |
| P109-4 | PTC Procedures & RCS Use - Yaw W/O Att. Hold    |

### B. TEST REQUIREMENTS

- 1. At least six uninterrupted hours of PTC in the translunar phase with the following conditions:
  - a. CSM (X) axis oriented perpendicular to the sun-spacecraft line and with the (-X) axis approximately perpendicular to the CSM-earth line of sight
  - b. Spacecraft attitude control in maximum deadband in pitch and yaw and roll free and rolling from 0.1 to 0.5 deg/sec.
- 2. At least six uninterrupted hours of PTC in the transearth phase with the following conditions:
  - a. CSM (X) axis oriented perpendicular to the sun-spacecraft line and with the (-X) axis approximately perpendicular to the CSM-earth line of sight
  - b. Spacecraft attitude control free in all axes with a roll rate of from 0.1 to 0.5 deg/sec
  - c. Deviation (coning) of (-X) axis from original orientation to be maintained to less than 15 degrees
- 3. If the above two modes are found to be inadequate during real time, at least six uninterrupted hours of PTC in the transearth phase with the following conditions:
  - a. CSM (+X) axis toward the sun with the high gain antenna boom on the earth side in the sun-earth-moon plane.
  - b. Spacecraft attitude control free with rotation about the major inertia axis at a rate of between 0.1 and 0.5 deg/sec
  - c. Deviations of rotational axis from original orientation to be maintained less than 7.5 degrees
- 4. Normal communications procedures evaluation during PTC

## C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph TBD meanwhile use "Special PTC Procedure"
- 2. "Passive Thermal Control Mode 1" (X Axis Roll, Pitch and Yaw Hold) or

- 3. "Passive Thermal Control Mode 2" (X Axis Roll W/O Pitch and Yaw Hold) or
- 4. "Passive Thermal Control Mode 3" (Yaw Z Axis with Pitch and Roll Free)

# D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Procedural difficulties in establishing, maintaining or terminating PTC (M)
  - Narration of procedure and results when establishing or correcting the PTC Mode (M)
  - c. Difficulties in establishing and maintaining S-band communications during the PTC Mode (M)
  - d. Log PTC maneuver correction times & difficulties on the Flight Plan timeline where they occur (M)

# 2. Ground Support

- a. CSM TM HBR (M)
- b. BÉT (M)
- c. MSFN records of received S-band signal strength (M)
- d. Flight Director reports of procedural and/or timeline difficulties or inadequacies (M)

# STAR/LUNAR HORIZON NAVIGATION

## A. TEST OBJECTIVES

| 11.00-2   | Star/Lunar Horizon Navigation Sighting Accuracy OSS Adequacy for Navigation Sightings in Deep Space |
|-----------|---|
| Pl.33-4   | RCS Propellant Use and Time to Assemblies of  |
| 020.117-0 | Photographs of Earth and Lunar Horizons   |

# B. TEST REQUIREMENTS

- 1. Use of the trunnion calibration option of P23 preceding a set of sightings if more than about 30 minutes has elapsed since the previous P23 trunnion calibration [1.33]
- 2. Translunar Near Earth
  - a. Five sets of star/lunar horizon sightings at more than 15,000 NM and less than 50,000 NM from the center of the earth [1.33]
  - b. Update of the onboard state vector utilizing the navigation sighting data following each set of sightings [1.33]

# 3. Transearth - Near Moon

- a. Fourteen sets of star/lunar horizon sightings at less than 50,000 NM from the center of the moon (1.33]
- Update of the onboard state vector utilizing the navigation sighting data following each set of sightings [1.33]
- At least 10 sequence photographs through the special sextant camera adapter while duplicating star/horizon navigation sightings when between 10,000 and 20,000 NM from the moon on the TE phase. It is desirable that these photographs be taken at varying distances [20.115] Not Implemented

# 4. Transearth - Midcourse

- a. Nineteen sets of star/lunar horizon sightings at more than 50,000 NM from the center of the moon [1.33]
- b. Update of the onboard state vector utilizing the navigation sighting data following each set of sightings [1.33]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.12.3 "Cislunar Midcourse Navigation (P23)" including "trunnion calibration" option
- 2. FCAC G-20A "P23 Cislunar Midcourse Navigation Measurement"
- 3. Photo checklist TBD

## D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - Difficulties and/or inadequacies noted in handling the optics and the spacecraft [1.33] (M)
  - b. Log navigation data on Flight Plan timeline [1.33] (M)
  - c. Photo log TBD [20.115] (HD)
- 2. Ground Support
  - a. CSM TM HBR [1.33] (M)
  - ь. вет [1.33] (M)

### STAR VISIBILITY

### A. TEST OBJECTIVES

S1.35-2 Obtain Data - Star Visibility During TL and TE Coast S1.35-3 Degradation of Navigation or IMU Alignment by Vented or Ejected Materials

### B. TEST REQUIREMENTS

- 1. Star visibility tests by observing the star field surrounding the navigation star targets of opportunity through the SCT and identifying the dimmest star in the star pattern under at least the following conditions:
  - a. Sun SCT LOS approximately 120°
  - b. Sun SCT LOS approximately 70°
- 2. Light adaptation period required prior to performing visibility tests
- 3. Evaluation of the effect of vented particles on the use of the optics during IMU realignments and navigation sightings

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.11.2 "IMU Realign (P52)" or
- 2. AOH paragraph 4.12.3 "Cislunar Midcourse Navigation (P23)"
- 3. FCAC G-39 "P52 IMU Realign" or
- 4. FCAC G-20A "P23 Cislunar Midcourse Navigation Measurement"

### D. DATA REQUIREMENTS

1. Flight Crew Reports/Logs

Identify and record dimmest star during each visibility test

2. Ground Support

BET during star visibility tests (M)

# LUNAR ORBIT INSERTION

### A. TEST OBJECTIVES

| S1.30-3 Overall GNCS Errors During Thrusting Maneu   | ivers                |
|--|----------------------|
| S3.21-1 SPS Isp - Adequacy of Conversion of Gnd. t   | to Vacuum Results    |
| S3 21-2 SPS Performance for LOI and TEI Burns        |                      |
| S3 21-4 Thermal Effects - Long SPS Burn - Heat Pro   | otection System      |
| P7 32-3 S-Band High Gain Antenna Dynamic Response    | During SPS Burns     |
| P20.105-1 Crew/Spacecraft/MSFN Preparation and Execu | ition of LOI Maneuve |
| P20.105-2 Procedures and Timeline Adequacy for LOI 1 | Maneuver             |

### B. TEST REQUIREMENTS

- SPS operation to insert the CSM into lunar orbit in two stages as follows [20.105]:
  - a. The first burn of approximately 245 seconds in duration will insert the CSM into a 60 x 170 NM orbit
  - b. The second burn of approximately 10 seconds in duration will circularize the orbit to  $60~\mathrm{NM}$
- 2. CSM fully loaded at liftoff [20.105]
- 3. FQTR ON for SPS thrust buildup, 5 sec at steady state and for thrust tailoff , during first LOI-1 only [7.32]
- 4. DSE recording immediately before, during, and after both burns [3.21]
- 5. DSE recording or TM for at least five seconds duration at approximately 15 minute intervals for about three hours after LOI-1 [3.21]
- 6. After LOI-1 it is HD to orient the CSM to an attitude that will result in a near constant external thermal environment to the SPS aft bulkhead during the subsequent 45 minute period. The aft bulkhead should be shielded from solar radiation during this period by orienting the (+X) axis toward the sun [3.21] N.I.
- 7. IMU realignment performed as soon prior to LOI-1 as practicable [20.105]
- C. TEST PROCEDURES/CHECKLISTS
  - 1. AOH paragraph 4.14.2 "G&N SPS Orbit Change Thrusting (P40)"
  - 2. FCAC G-32 "SPS Thrusting (P40)"
- D. DATA REQUIREMENTS
  - 1. Flight Crew Reports/Logs
    - a. Procedural and/or timeline difficulties or inadequacies [20.105] (M)

- b. Feasibility of monitoring abort parameters on FDAI's [20.105] (M)
- c. Adequacy of contact with ground operational support [20.105] (HD)
- d. If the PU valve position is changed, record GET  $\stackrel{+}{-}$  1 sec and new valve position [3.21] (M)

# 2. Ground Support

- a. CSM TM LBR [20.105] (M)
- b. BET [3.21] (HD), [20.105] (M)
- c. Flight Director reports of procedural and/or timeline difficulties or inadequacies [20.105] (M)

# LUNAR LANDMARK TRACKING

## A. TEST OBJECTIVES

- P20.111-1 Error Uncertainties in Lunar Landing Site Location
- P20.111-2 Obtain Data to Calibrate MSFN at Lunar Distance
- P20.111-3 Determine Minimum Sun Angle to Clearly Identify Lunar Landmarks
- P20.111-4 Lunar Landmark Tracking in Earthshine
- P20.111-5 Adequacy of CSS and OSS for Obtaining Landmark Sightings
- P20.111-6 Crew Ability to Coordinate Landmark Sightings and Vehicle Maneuvers
- P20.111-7 RCS Propellant and Time Required for Landmark Sighting

## B. TEST REQUIREMENTS

- 1. At least 12 sets of four marks each obtained on four selected landmarks according to the following schedule:
  - a. Track a pre-selected pseudo landing site (same terrain and lighting as the lunar landing site) for four consecutive revolutions. The sun elevation angle to be five degrees on the first tracking orbit
  - b. Track three pre-selected landmarks (or others deemed acceptable by the crew). The same three landmarks to be tracked in a four orbit tracking sequence. It is highly desirable that the sun angle be greater than 60 degrees.
  - c. An attempt made to track a landmark at a sun elevation angle of three degrees
- 2. On one revolution, CMP verbal description of the terrain near the sunrise terminator as observed through the scanning telescope. The observation to be made from about 10° preceding the terminator to about 15° past the terminator in the earthlit portion of the dark side. The optics angle to be fixed and the spacecraft in an orbital rate mode.
- 3. If the observations made of the earthlit landmarks reveals that it is feasible, it is highly desirable that the crew track two landmarks (four marks each) on two successive earthlit passes.
- 4. IMU realigned during the dark pass preceding each tracking sequence
- 5. DSE Tape Recorder ON for 20 seconds following each set of marks while N49 ( $\Delta R$ ,  $\Delta V$ ) displayed
- 6. ORDEAL functioning

7. Photographic records of each of the four tracked landmarks using the special sextant camera adapter and D. A. camera at 12 Fps and taking the photographs at the same time as making the MARK during sighting. Take one photograph of each landmark on two consecutive passes (i.e., eight pictures)

# C. TEST PROGEDURES/CHECKLISTS

- 1. AOH paragraph 4.12.2, "Orbital Navigation (P22)"
- 2. FCAC G-18 "P22 Orbital Navigation"
- 3. FCAC "Lunar Landmark Tracking" TBD
- 4. Reference Photographic Operation's Plan, Apollo 8

## D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Verbal description of lunar terrain during earthshine landmark lighting evaluation (M)
  - Comments on the effect of earthshine while tracking lunar landmarks (M)
  - c. Procedural and/or timeline difficulties or inadequacies (M)
  - d. "Landmark Tracking Log" (Flight Plan)
  - e. Photo log
    - 1. Film mag IP
    - 2. GET camera ON
    - 3. Initial shutter speed
    - 4. Final shutter speed
    - 5. Estimated remaining film at beginning and end of a sequence

### PHOTOGRAPHY

### A. TEST OBJECTIVES

- 1.35-3 Photographs of Vented Particles Through Windows
- 20.115-1 Overlapping Photographs from Terminator to Terminator Lunar Orbit
- 20.115-3 Photographs of Earth and Lunar Landmarks
- 20.115-4 Photographs of General and Scientific Interest

### B. TEST REQUIREMENTS

- 1. Terminator-to-terminator photographs on at least two passes as follows:
  - a. The first pass consisting of vertical photos with 55-60% forward overlap taken at 20 sec intervals
  - b. The subsequent pass consisting of photos taken with the camera axis 20° from local vertical. From the far side terminator to 90° sun elevation at the nadir, the camera axis will be inclined 20° foreward along the orbital plane. At 90°, the camera axis will be aligned 20° aft of the nadir in the orbital plane
- Sequence camera photographs if possible of the following targets of opportunity:
  - a. Vertical zero phase (250 mm lens)
  - b. High angle zero phase: Apollo landing sites and geologic units (250 mm lens)
  - c. Vertical terminator (250 mm lens)
  - d. Oblique terminator (250 mm lens)
  - e. Specific feature near vertical and oblique (250 mm)
  - f. Specific area near vertical (80 mm)
  - g. Lunar exploration site:
    - (1) Near vertical or oblique as required (250 mm lens)
    - (2) Approach (250 mm lens)
  - h. Surveyor landing sites (250 mm lens)
  - i. Other features and phenomena as observed (250 mm lens)
  - j. Image motion compensation (250 mm lens)

- 3. Dim light and astronomical photos attempted either during TL or TE coast or during dark portion of lunar orbits
  - a. Total darkness preferred -- S/C lighting also as low as possible
  - b. Specific star fields should be taken during TL and TE coast and in lunar orbit during earthshine
- 4. Photos taken of the lunar surface during earthshine
- 5. Solar corona photos taken at sunrise or sunset in lunar orbit using the moon as an occultating disc
- 6. Earth photos during TL coast when the S/C is within 40,000 NM of the earth. The S/C shall be oriented with the  $(\pm X)$  axis toward earth for approximately 10 minutes for these photos
- 7. Sequence camera photographs of the lunar terrain as viewed through the rendezvous window while duplicating the Post LOI-2 approach attitude of missions F and G.
- 8. Photographs of vented particles through windows when observed
- C. TEST PROCEDURES/CHECKLISTS
  - 1. Photographic Operation Plan for Apollo Mission C'
- D. DATA REQUIREMENTS
  - 1. Flight Crew Reports/Logs
    - a. Photos of lunar surface per Test Requirement No. 1 above (M)
    - Photos of scientific and general interest subjects as defined by photo plan (HD)
  - 2. Ground Support

BET (M)

# TRANSEARTH INSERTION

#### TEST OBJECTIVES Α.

- SPS Isp Adequacy of Conversion of Ground to Vacuum Results S3.21-1
- SPS Performance for LOI and TEI Burns
- SPS PUGS in Auxiliary Mode Relative Accuracy of Aux and Pri s3.21-2
- Thermal Effects Long SPS Burn Heat Protection System S3.21-3
- P20.106-1 Crew/Spacecraft/MSFN Preparation and Execution of TEI Maneuver
- P20.106-2 Procedures and Timeline Adequacy for TEI Maneuver

#### TEST REQUIREMENTS В.

- SPS use for injection of the CSM into transearth coast [3.21]
- DSE recording of TM for the period 40 seconds prior to, during, and two minutes after the TEI burn [3.21, 20.116]
- DSE recording or TM of at least five seconds duration at approximately 15 minute intervals for about three hours after TEI [3.21]
- 4. PUGS mode switch in the AUX position during the SPS burn [3.21]
- 5. After the burn it is HD to orient the CSM to an attitude that will result in a near constant external thermal environment to the SPS during the subsequent 45 minute period. The aft bulkhead should be shielded from solar radiation during this period by orienting the (+X) axis toward the sun [3.21] - N.I.
- 6. IMU realignment performed as soon before TEI as practicable [20.106]
- CMC update provided on a timeline similar to the LLM such that errors at T can be determined and compared with predicted estimates [20.106]

# TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.14-2 "G&N SPS Orbit Change Thrusting (P40)"
- FCAC G-32 "SPS Thrusting (P40)"

# DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Adequacy of contact with ground operational support [20.106] (HD)
  - If the PU valve position is changed, record GET  $\stackrel{+}{-}1$  sec and new valve position [3.21] (M)

# 2. Ground Support

- 1. CSM TM LBR [3.21, 20.106] (M)
- 2. BET [3.21] (HD), [20.106] (M)
- 3. Flight Director reports of procedural and/or timeline difficulties or inadequacies [20.106] (M)
- 4. Flight Operations Plan [20.106] (M)

### ENTRY

### A. TEST OBJECTIVES

- 1.31-1 GNCS Performance During Entry Lunar Return
  1.31-2 EMS Capability to Monitor Entry Lunar Return
  4.5-1 ECS Performance During Manned Lunar Return Entry
  4.5-2 Compare ECS Data With Development Model & Unmanned Results
  7.30-1 Block II Thermal Protection System Manned Lunar Return Entry
- 7.30-1 Block II Thermal Protection System Manned Lunar Return En 7.30-2 TPS Surface Recession and Char Data Comparison With Models
- 20.116-2 Changes in Total Transmittance of Windows

### B. TEST REQUIREMENTS

- 1. Entry velocity at 400,000 ft. altitude at least 36,000 feet per second [7.30]
- 2. Automatic lunar return entry nominal range 1350 NM and 2500 NM maximum for inclement weather [1.31]
- 3. DSE ON during entry "blackout" recorder fully rewound and on HBR starting at CSM/SM separation [1.31]
- 4. Crew monitor the EMS and record voice on the DSE during entry [1.31]

# C. TEST PROCEDURES/CHECKLISTS

- 1. AOH paragraph 4.17.7, "G and N Entry"
- 2. FCAC "Entry"

### D. DATA REQUIREMENTS

- 1. Flight Crew Reports/Logs
  - a. Comments on adequacy of DSKY, FDAI and EMS displays to evaluate entry conditions [1.31] (HD)
  - b. Comments on crew comfort [4.5] (HD)

### 2. Ground Support

- a. CSM TM HBR [1.31, 4.5] (M)
- b. BET [1.31, 7.30] (M)
- c. EMS Scroll Recovery [1.31] (M)
- d. CM Recovery [7.30] (M)
- e. Heat Shield core sample after recovery [7.30] (M)
- f. All S/C window outer panes after recovery [20.116] (M)

### MISCELLANEOUS TESTS

### A. TEST OBJECTIVES

| r/.31-1   | Inermal Control System During PTC                   |
|-----------|---|
| P7.31-2   | Thermal Control System During Lunar Orbit           |
| P20.107-1 | Crew Procedures for Lunar Orbit Mission             |
|           |   |
| S20.108-1 | EPS Use, Performance and Fuel Cell Management       |
| S20.108-2 | Water and Oxygen Requirements Data                  |
|           | LiOH Cartridge Requirements Data                    |
| S20.108-4 | SPS, SM/RCS & CM/RCS Propellant Requirements Data - |
|           | Translation and Attitude Maneuvers                  |
| S20.108-5 | Crew Food Requirements Data                         |
|           |   |
|           |   |

### B. TEST REQUIREMENTS

- 1. Operation of the CSM in lunar orbit, undocked to determine the thermal properties of the spacecraft insulation [7.31]
- 2. Determination of the effectiveness of the thermal control system to provide a safe environment for operation of spacecraft equipment and consumables [7.31]
- 3. Accomplishment of all CM procedures peculiar to the lunar orbit mission in the same manner, where possible, as required for the LLM [20.107]
- 4. Management of the EPS during the lunar mission per the flight plan [20.108]
- 5. Utilization of the potable water produced during EPS operation as necessary [20.108]
- 6. Utilization of the oxygen supply system during the lunar mission as required [20.108]
- 7. Management of the replacement of LiOH cartridges during the mission per the flight plan [20.108]
- 8. Management of the consumption of the SPS and RCS propellants during the lunar mission as required [20.108]
- 9. Utilization of the food supply per the flight plan [20.108]
- 10. Performance of operational ground support of the spacecraft throughout the mission with emphasis on those phases being accomplished for the first time as part of a lunar orbit mission [20.110]

- C. TEST PROCEDURES/CHECKLISTS
  - 1. AOH CSM 103 SM2A-03-SC103-2
  - 2. FCAC CSM 103
- D. DATA REQUIREMENTS
  - 1. Flight Crew Reports/Logs
    - Narrative describing any recommended changes in procedures and/or equipment required to accomplish the procedures [20.107] (M)
    - b. Comments on any procedure requiring repeating or any procedure not completed [20.107] (M)
    - c. Water Count Log [20.108] (M)
    - d. LiOH Log [20.108] (M)
    - e. Astronaut Menus [20.108] (HD)
    - f. Comments on ECS environment comfort level [20.108] (HD)
  - 2. Ground Support
    - a. CSM TM HBR [7.31, 20.108] (M)
    - b. BET [7.31, 20.108] (M)
    - c. MSFN voice recording of CSM/MSFN communications [20.107] (HD)
    - d. Chemical analysis of recovered LiOH cartridges [20.108] (M)
    - e. Measurement of recovered water quantity [20.108] (M)
      - f. Measurement of energy remaining in recovered Entry and Post-Landing Batteries [20.108] (M)
      - g. Flight Director reports of mission support activities [20.110] (M)

# **TELECOMMUNICATIONS**

# A. TEST OBJECTIVES

| S6.10-1   | S-Band Performance with Omni Antennas at Lunar Distance (85' MSFN)   |
|-----------|--|
| S20.104-3 | S-Band Performance with High Gain Antenna During TL Coast<br>S-Band Performance with High Gain Antenna at Lunar Distance<br>S-Band Communications Performance During Transposition<br>Communications Procedures During PTC |

# B. TEST REQUIREMENTS

1. Continuous CSM/MSFN S-band communication during transposition using CSM omni and 85' ground antennas [20.104]

| Signal      |                     | cati | ons Mode |       |           |     |
|-------------|---------------------|------|----------|-------|-----------|-----|
| Combination | <u>Uplink</u>       |      | <u>D</u> | ownli | <u>nk</u> |     |
| 4.2         | Carrier, PRN, Voice | _    | Carrier, | PRN.  | Voice.    | HBR |

2. MSFN performance of various designated S-band communication mode tests of at least two minutes each as soon as practical after high gain antenna deployment (near earth) using the 85' ground antenna and the CSM high gain antenna as follows: [6.11]

| Signal<br>Combination | <u>Up</u> | C<br><u>link</u> | ommunic | ati | ons Mode<br>D | ownli: | nk     |     |
|-----------------------|-----------|------------------|---------|-----|---------------|--------|--------|-----|
| 4.2                   | Carrier,  | PRN;             | Voice   | -   | Carrier,      |        |        | HBR |
| 6.2                   |           |                  |         |     | Carrier,      |        |        |     |
| . 2                   |           |                  |         |     | Recorded      | voice  | LBR    |     |
| 4.3                   | Carrier,  | PRN,             | Voice   | _   | Carrier,      |        |        | LBR |
| 6.3                   |           |                  |         |     | Carrier,      |        |        |     |
| 5.2                   | Carrier,  | PRN,             | Updata  |     | Carrier,      | PRN,   | Voice, | HBR |
| 8.1                   |           |                  |         |     | Carrier,      |        |        |     |
| . 4                   |           |                  |         |     | CSM telev     |        | -      |     |

3. MSFN performance of various designated S-band communication mode tests at lunar distance using 85' ground antenna or equivalent lunar distance using 30' ground antenna\* and the CSM omni antennas [6.10]

\*NOTE: The test can be accomplished under any one of the three following conditions which represent lunar distance or equivalent:

- a. Greater than 200 K NM with 85-foot dish (preferred)
- b. At 100 K + 10% NM with cooled 30-foot dish (HAW, CWM, ASC, CRO)
- c. At 70 K  $\pm$  10% NM with uncooled 30-foot dish (others)

| Signal<br>Combination | Communications Mode <u>Uplink</u> <u>Downlink</u> |                         |  |  |  |
|-----------------------|---|-------------------------|--|--|--|
| • 5                   |   | Carrier, LBR            |  |  |  |
| .6                    |   | Carrier, Key Subcarrier |  |  |  |
| 1.7                   | Carrier, PRN                                      | - Carrier, PRN          |  |  |  |
| .8                    | <i>)</i>  | Carrier, BU Voice, LBR  |  |  |  |
| .10                   |   | Carrier, BU Voice       |  |  |  |

4. MSFN performance of various designated S-band communication mode tests at lunar distance using 85' ground antenna or equivalent lunar distance using 30' ground antenna\* and CSM Hi gain antenna [6.11]

| Signal      | Communic             | ati | ons Mode |        |           |     |
|-------------|----------------------|-----|----------|--------|-----------|-----|
| Combination | <u>Uplink</u>        |     | Do       | ownlir | <u>ık</u> |     |
| . 4.2       | Carrier, PRN, Voice  | *** | Carrier, | PRN,   | Voice,    | HBR |
| 5.2         | Carrier, PRN, Updata | ι — | Carrier, | PRN,   | Voice,    | HBR |
| 4.3         | Carrier, PRN, Voice  | _   | Carrier, | PRN,   | Voice,    | LBR |
| 8.1         | Carrier, BU Voice    | _   | Carrier, | Voice  | e, LBR    |     |

- 5. During steerable S-band antenna tests, demonstration of manual acquisition and automatic tracking using wide, medium and narrow beamwidths
- C. TEST PROCEDURES/CHECKLISTS
  - 1. AOH Section 4.7.6, "Telecommunications", paragraphs 4.7.6.1 through 4.7.6.10
  - 2. FCAC communications checklist TBD
- D. DATA REQUIREMENTS
  - Flight Crew Reports/Logs

Comments on voice quality in flight plan [6.10, 6.11 & 20.104] (M)

- 2. Ground Support
  - a. CSM TM HBR [6.10, 6.11] (M)
  - b. CSM MSFN Voice records [6.10, 6.11, 20.104]

\*NOTE: The test can be accomplished under any one of the three following conditions which represent lunar distance or equivalent:

- a. Greater than 200 K NM with 85-foot dish (preferred)
- b. At 100 K  $\pm$  10% NM with cooled 30-foot dish (HAW, CWM, ASC, CRO)
- c. At 70 K  $\pm$  10% NM with uncooled 30-foot dish (others)

- c. Flight Director reports of procedural and/or timeline difficulties or inadequacies in implementing all required communication tests [6.10, 6.11, 20.104] (HD)
- d. USB TM bit stream [6.10, 6.11, 20.104] (M)
- e. USB tracking data processor output [6.10, 6.11] (HD), [20.104] (M)
- f. MSFN records of received S-band carrier strength [6.10, 6.11, 20.104] (M)
- g. MSFN tape recordings of CSM to MSFN emergency key mode [6.10] (M)

# APOLLO 8 CREW STATUS REPORTS

## Purpose:

- 1. To enhance crew safety.
- 2. To acquire data on food, water, sleep and exercise requirements for future mission planning.
- 3. To obtain medical data required for analysis and correlation with the inflight bioenvironmental data and the pre- and postflight physical examination results.

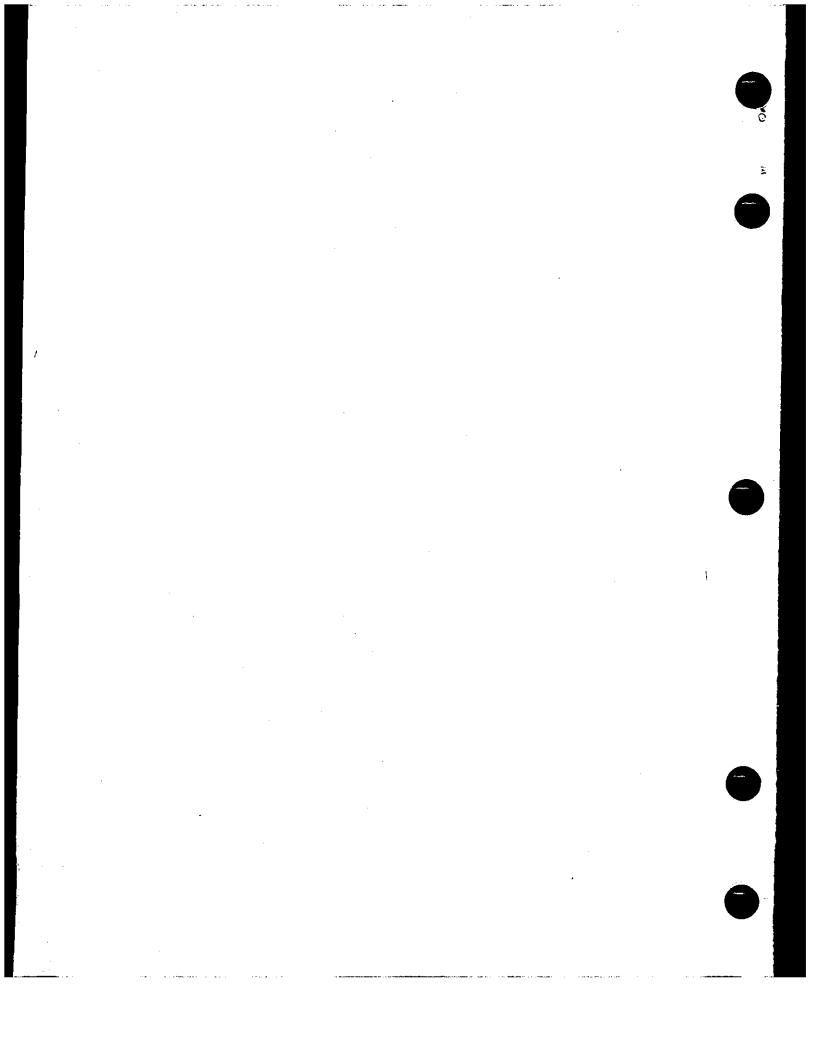
# Requirements:

To obtain food, water, sleep and radiation data during the Apollo 8 mission and exercise data postflight.

## Procedures:

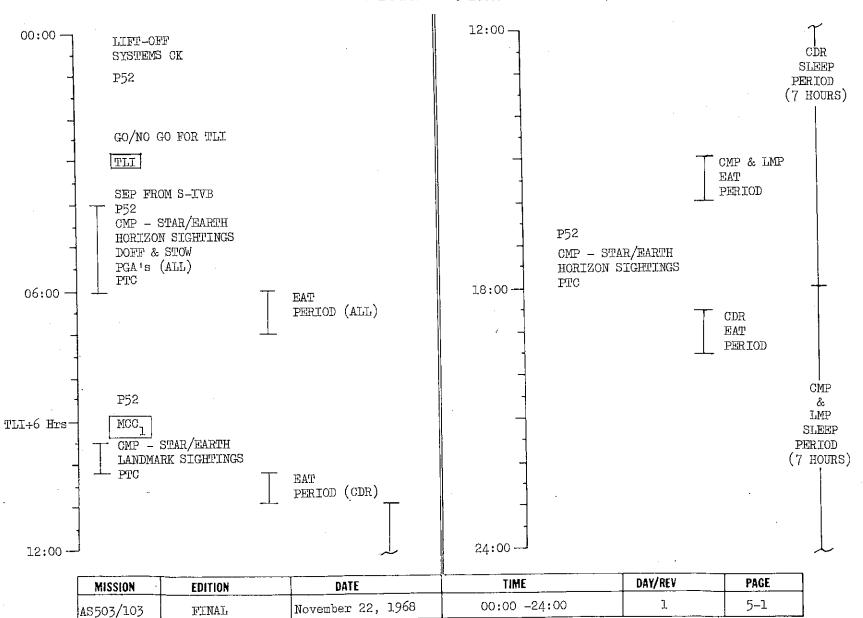
During the Apollo 8 mission, two crew status reports via air-to-ground communications will be made by the flight crew during each 24-hours ground elapsed time (GET). The first report will be given after the first meal of the work day and will concern the sleep obtained during the previous sleep period. The second report will be given following the final meal of the work day and will concern the food and water consumed, and the radiation dose received during the previous 24 hours GET. The following information should be transmitted:

- 1. Food a daily record of each crew member reflecting the meal identification code together with the description or serial number(s) of only those items not consumed from a scheduled meal.
- 2. Water a daily log containing the number of aliquots from the water gun each astronaut drank. Water used for food rehydration will not be recorded.
- 3. Sleep a daily notation of each crewman's best estimate as to sleep quantity and quality.
- 4. Radiation a daily record of the integrated dose each crewman receives.
- 5. Exercise (postflight analysis only) a daily record of the time of exercise, the type, and the duration of exercise performed by each astronaut.



SECTION V - SUMMARY FLIGHT PLAN

# FLIGHT PLAN



MSC FORM 1186 (SEP 67)

FLIGHT PLANNING BRANCH

### FLIGHT PLAN 24:00-36:00-CDR EATPERIOD EAT PERIOD (ALL) CMP & P52 CMP - STAR/EARTH LMPSLEEP HORIZON SIGHTINGS PERIOD (7 HOURS) TLI + 25 Hrs -MCC2 CMP - STAR/EARTH HORIZON SIGHTINGS PTC 30:00 42:00 CMP & LMP EAT PERIOD TVEAT PERIOD (ALL) P52 CDR SLEEP CMP - STAR/LUNAR PERIOD HORIZON SIGHTINGS P52 (7 HOURS) CMP - STAR/EARTH HORIZON SIGHTINGS - MCC<sub>3</sub> CMP - STAR/EARTH PTC LOI -22 Hr-CMP & LMP EAT PERIOD L HORIZON SIGHTINGS 36:00 48:00 MISSION **EDITION** DATE TIME DAY/REV PACE

MSC FORM 1186 (SEP 67)

FINAL

AS503/103

FLIGHT PLANNING BRANCH

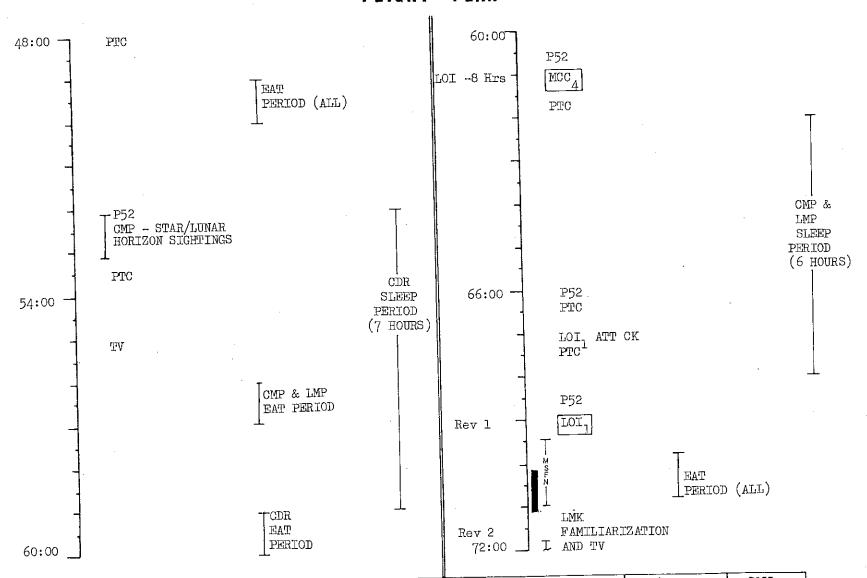
24:00 - 48:00

November 22, 1968

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# FLIGHT PLAN



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 AS 503/103
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 November 22, 1968
 48:00 - 72:00
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MSC FORM 1186 (SEP 67)

FLIGHT PLANNING BRANCH

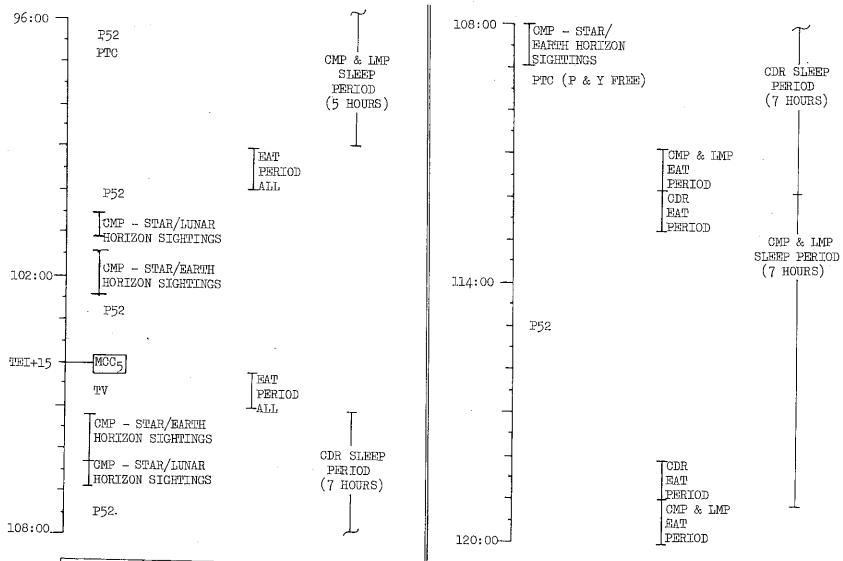
#### FLIGHT PLAN 72:00-84:00 T LDG SITE DARKSIDE CMP REST PHOTOGRAPHY Rev 3 PERIOD CONVERGENT STERO Rev 9 (2 HOURS) AND TV TRAINING PHOTOS CMP REST PERIOD (2 HOURS) Rev 4 EAT VERTICAL STERO Rev 10 PERIOD (ALL) LMK LIGHTING EVAL P52 P52 CDR Rev 5 LEAT PERIOD 89:15 TEI LMK SIGHTING (1) LDG SITE 78:00 **ISIGHTING** P52 90:00 -P52 CMP - STAR/LUNAR CDR REST HORIZON SIGHTINGS PERIOD Rev 6 LMK SIGHTING (1) LDG SITE (3 HOURS) SIGHTING P52 PTCCDR SLEEP PERIOD LMP(5 HOURS) EAT PERIOD Rev 7 LMK SIGHTINGS (3) CMP & LMP LDG SITE EAT PERIOD SIGHTING $^{ m CDR}$ LMP REST EAT PERIOD CMPPERIOD LMK SIGHTINGS (3) Rev 8 (2 HOURS) & LMP 84:00-SLEEP PERIOD 96:00\_ (5 HOURS)

| MISSION     | EDITION     | DATE              | <u> </u>       | — <sub>{</sub> |          |
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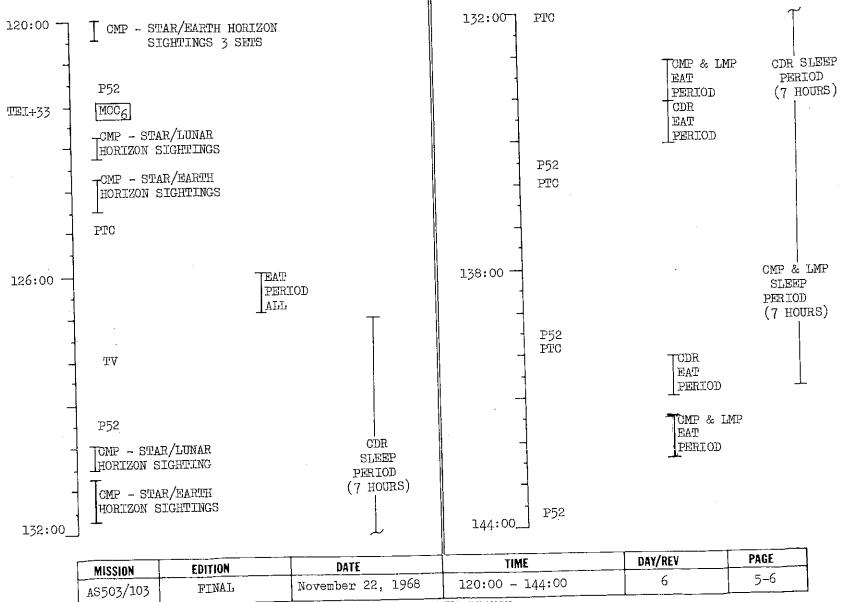
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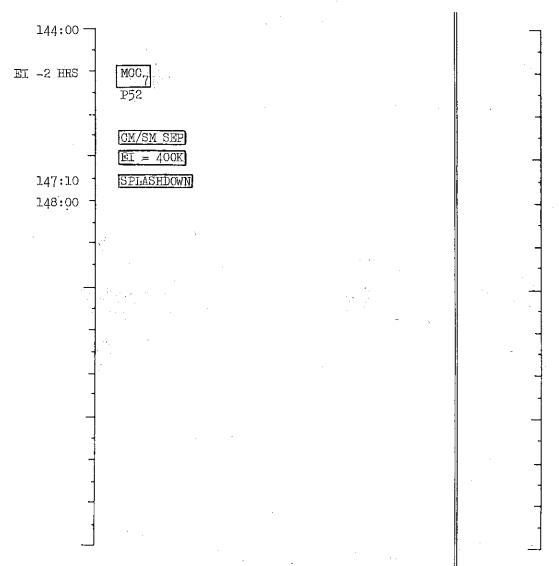
MSC FORM 1186 (SEP 67)

FLIGHT PLANNING BRANCH





# FLIGHT PLAN



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MSC FORM 1186+ (SEP 67)

FLIGHT PLANNING BRANCH